GLENTEK ANALOG BRUSH PWM SERVO DRIVES MODELS: SMB7230

Revision: 8/7/2020



Glentek's Analog Brush PWM Servo Drives offer high performance analog control of brush type rotary and voice coil motors. Both AC powered (stand alone and multi-axis) and DC powered (module) packages are available. Glentek has been designing and manufacturing analog brush PWM servo drives for over 40 years and continually updates each product as advances in technology become available so that customers are assured of optimal performance and reliability. These drives offer a cost effective, simple (tuning is accomplished by the adjustment of potentiometers) and high performance solution.

ELECTRICAL RATINGS							
Madal Number	Input Voltage		Continuous	Peak	Available Package Configurations		
Model Number	VDC	VAC	Current (A)	Current (A)	Module	Stand Alone	Multi-Axis
SMB7230	N/A	60-120	30	60		•	

Command/Control Modes		
+/-10 VDC for current (torque)		
+/-10 VDC for velocity (RPM)		
Feedback		
Analog tachometer (required for velocity control)		
Dedicated Inputs		
Single-ended or differential signal command, tachometer, +/- limits, inhibit/enable, fault, reset		
Motor temperature		
Master slave		
Dedicated Outputs		
Motor current, fault, low-speed electronic circuit breaker, high-speed electronic circuit breaker,		
over-voltage and over-temperature		

FEATURES

Performance				
Current limit	Peak motor current is adjustable.			
Frequency response	2 kHz minimum for current loop and 750 Hertz minimum for velocity loop.			
Fault protection	Short from output to output, short from output to ground, drive RMS over current, drive under/over voltage and drive over temperature.			
Silent operation	18 kHz PWM standard.			
External fault reset	Can reset drive externally in the event of a fault condition.			
	Feedback			
Tachometer	Required for velocity feedback.			
	Dedicated I/O			
+/- Limits & inhibit	Three separate logic inputs can stop the motor in either or both directions. Inputs may be con figured for active-high or active-low, pull-up or pull down termination, and a 0 to +5 VDC or 0 to +15 VDC range.			
Dual signal inputs	One single-ended and one differential. Both inputs may be used simultaneously. Both have up to $15,000A/V$ gain (velocity mode), and inputs will accept the typical ± 10 VDC analog signal.			
Fault input/output	Open-collector output goes low in the event of a fault. Forcing the fault terminal low will inhibit the drive. The fault terminals outputs in a multi-axis system may be connected together to shut down all drives should any drive have a fault.			
Master/slave				
Input				
Operating voltage	The Stand Alone version can be ordered for operation from 60-120 VAC (single or 3-phase, 50/60 Hz).			
Direct AC operation	The stand alone units include a DC bus power supply, cooling fans and a regen clamp with dumping resistor.			
Build				
Complete isolation	Complete isolation between signal and power stage.			
LED diagnostics	Display various fault and operating conditions.			
Short circuit protection	Complete short circuit and ground fault protection.			
SMT construction	Provides ultra compact size, cost competitive package and high reliability.			
Ergonomic design	Easy access to connections, adjustments, and test points.			

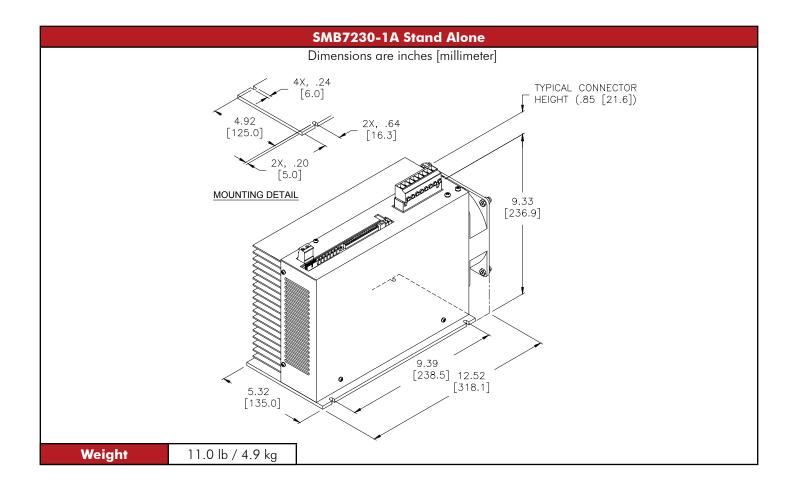
ENVIRONMENTAL CONDITIONS			
Storage Temperature:	-40°C to 80°C		
Operating Temperature:	Standard: 0°C to 40°C without current derating, up to 50°C with 25% current derating Special: -40°C to 40°C without current derating, up to 50°C with 25% current derating		
	5% to 95% relative humidity, non-condensing		
Altitude:	Up to 1000m without derating, derate current 10% per 1000m above 1000m		

DIMENSIONS

Mounting Configurations

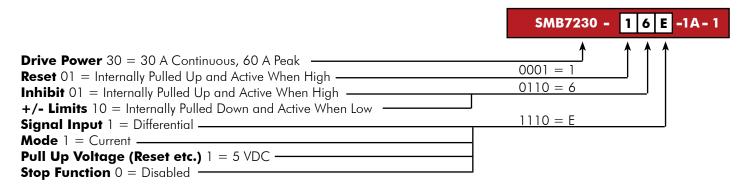
Stand Alone

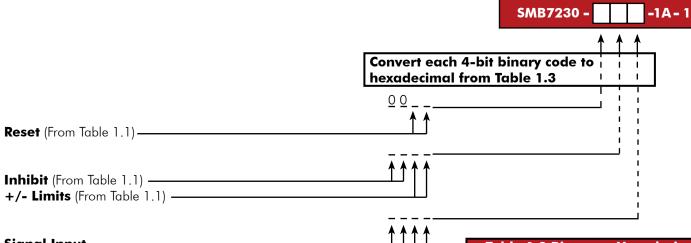
This package consists of a drive module, DC bus power supply, regen clamp with dumping resistor, in-rush current limiting protection at power-on, fuses and one or more cooling fans. This type of package is typically used for one or multi-axis applications.



STAND ALONE MODEL NUMBERING

This section explains the model numbering system for Glentek's Analog Brush PWM servo drives. The model numbering system is designed so that you, our customer, will be able to create the model number for the drive that best suits your needs. In order to accurately select a complete model number, please choose the model and package configuration you require based on its electrical ratings. Then complete the drive configuration code you require using the information on this page. After completing your model number, be sure to contact a Glentek Sales Engineer to confirm that the model number you have created is correct.





Signal Input 0 = Single Ended 1 = Differential	
Mode 0 = Velocity 1 = Current	
Pull Up Voltage (Reset etc.) 0 = 15 VDC 1 = 5 VDC	

Stop Function — 0 = Disabled 1 = Enabled

Table 1.3 Binary to Hexadecimal Conversion				
Binary Hex Binary Hex				
0000	0	1000	8	
0001	1	1001	9	
0010	2	1010	Α	
0011	3	1011	В	
0100	4	1100	С	
0101	5	1101	D	
0110	6	1110	Е	
0111	7	1111	F	

Table 1.1 Inhibit, Reset, +/- Limits Configuration				
Туре	Input is:	Input State:	Binary	
Α	Internally Pulled Up	Active When Low	00	
В	Internally Pulled Down	Active When High	11	
С	Internally Pulled Up	Active When High	01	
D	Internally Pulled Down	Active When Low	10	

Table 1.2 Logic Input Configuration			
Туре	Logic		
Α	Requires grounding of input to disable the drive.		
В	Requires a positive voltage at input to disable the drive.		
С	Requires grounding of input to enable the drive.		
D	Requires a positive voltage at input to enable the drive.		