## GLENTEK ANALOG BRUSH PWM SERVO DRIVES MODELS: SMB7245

Revision: 8/7/2020



Glentek's Analog Brush PWM Servo Drives offer high performance analog control of brush type rotary and voice coil motors. Both AC powered (stand alone and multi-axis) and DC powered (module) packages are available. Glentek has been designing and manufacturing analog brush PWM servo drives for over 40 years and continually updates each product as advances in technology become available so that customers are assured of optimal performance and reliability. These drives offer a cost effective, simple (tuning is accomplished by the adjustment of potentiometers) and high performance solution.

ELECTRICAL RATINGS							
Madel Number	Input Voltage		Continuous Peak	Available Package Configurations			
Model Number	VDC	VAC	Current (A)	Current (A)	Module	<b>Stand Alone</b>	Multi-Axis
SMB7245	N/A	60-120	45	80		•	

Command/Control Modes
+/-10 VDC for current (torque)
+/-10 VDC for velocity (RPM)
Feedback Peedback
Analog tachometer (required for velocity control)
Dedicated Inputs
Single-ended or differential signal command, tachometer, +/- limits, inhibit/enable, fault, reset
Motor temperature
Master slave
Dedicated Outputs
Motor current, fault, low-speed electronic circuit breaker, high-speed electronic circuit breaker,
over-voltage and over-temperature

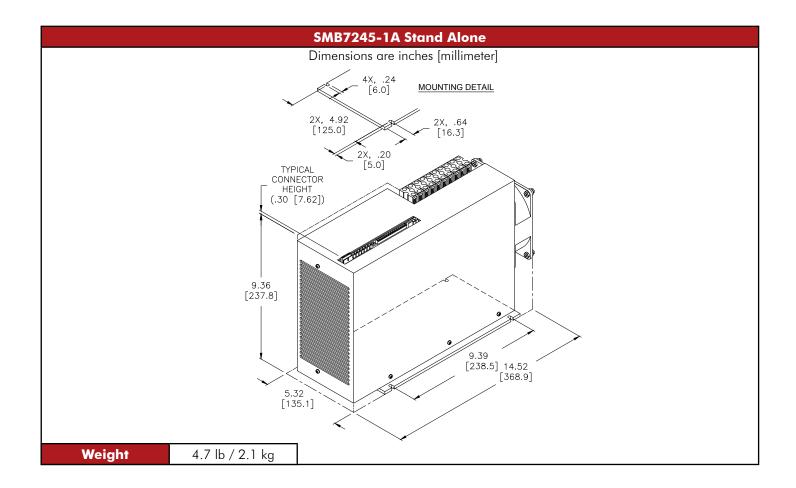
### **FEATURES**

	Performance		
Current limit	Peak motor current is adjustable.		
Frequency response	2 kHz minimum for current loop and 750 Hertz minimum for velocity loop.		
Fault protection	Short from output to output, short from output to ground, drive RMS over current, drive under/over voltage and drive over temperature.		
Silent operation	18 kHz PWM standard.		
External fault reset	Can reset drive externally in the event of a fault condition.		
	Feedback		
Tachometer	Required for velocity feedback.		
	Dedicated I/O		
+/- Limits & inhibit	Three separate logic inputs can stop the motor in either or both directions. Inputs may be configured for active-high or active-low, pull-up or pull down termination, and a 0 to $+5$ VDC or 0 to $+15$ VDC range.		
Dual signal inputs	One single-ended and one differential. Both inputs may be used simultaneously. Both have up to 15,000A/V gain (velocity mode), and inputs will accept the typical $\pm 10$ VDC analog signal.		
Fault input/output	Open-collector output goes low in the event of a fault. Forcing the fault terminal low will inhibit the drive. The fault terminals outputs in a multi-axis system may be connected together to shut down all drives should any drive have a fault.		
Master/slave			
	Input		
Operating voltage	The Stand Alone version can be ordered for operation from 60-120 VAC (single or 3-phase, 50/60 Hz).		
Direct AC operation	The stand alone units include a DC bus power supply, cooling fans and a regen clamp with dumping resistor.		
	Build		
Complete isolation	Complete isolation between signal and power stage.		
LED diagnostics	Display various fault and operating conditions.		
Short circuit protection	Complete short circuit and ground fault protection.		
SMT construction	Provides ultra compact size, cost competitive package and high reliability.		
Ergonomic design	Easy access to connections, adjustments, and test points.		

ENVIRONMENTAL CONDITIONS		
Storage Temperature:	-40°C to 80°C	
Operating Temperature:	Standard: 0°C to 60°C with 2.86% current derating per °C above 25°C Special: -40°C to 70°C with 2.22% current derating per °C above 25°C	
	5% to 95% relative humidity, non-condensing	
Altitude:	1000m, for applications at higher altitudes, please contact a Glentek sales engineer	

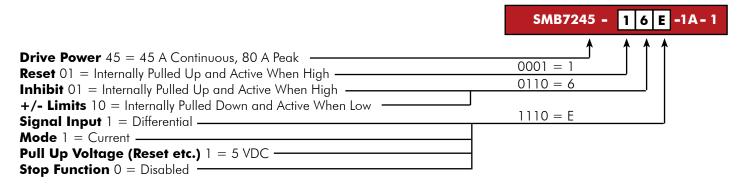
#### **DIMENSIONS**

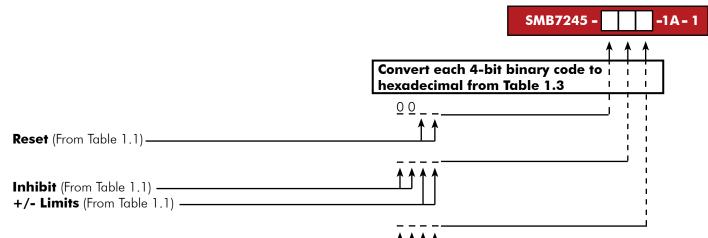
# Mounting Configurations This package consists of a drive module, DC bus power supply, regen clamp with dumping resistor, in-rush current limiting protection at power-on, fuses and one or more cooling fans. This type of package is typically used for one or multi-axis applications.



#### STAND ALONE MODEL NUMBERING

This section explains the model numbering system for Glentek's Analog Brush PWM servo drives. The model numbering system is designed so that you, our customer, will be able to create the model number for the drive that best suits your needs. In order to accurately select a complete model number, please choose the model and package configuration you require based on its electrical ratings. Then complete the drive configuration code you require using the information on this page. After completing your model number, be sure to contact a Glentek Sales Engineer to confirm that the model number you have created is correct.





Signal Input  0 = Single Ended  1 = Differential	
Mode 0 = Velocity 1 = Current	
Pull Up Voltage (Reset etc.)  0 = 15 VDC  1 = 5 VDC	

Stop Function -0 = Disabled 1 = Enabled

Table 1.3 Binary to Hexadecimal Conversion			
Binary	Hex	Binary	Hex
0000	0	1000	8
0001	1	1001	9
0010	2	1010	Α
0011	3	1011	В
0100	4	1100	С
0101	5	1101	D
0110	6	1110	Е
0111	7	1111	F

Table 1.1 Inhibit, Reset, +/- Limits Configuration				
Туре	Input is:	Input State:	Binary	
Α	Internally Pulled Up	Active When Low	00	
В	Internally Pulled Down	Active When High	11	
С	Internally Pulled Up	Active When High	01	
D	Internally Pulled Down	Active When Low	10	

Table 1.2 Logic Input Configuration			
Туре	Logic		
Α	Requires grounding of input to disable the drive.		
В	Requires a positive voltage at input to disable the drive.		
С	Requires grounding of input to enable the drive.		
D	Requires a positive voltage at input to enable the drive.		