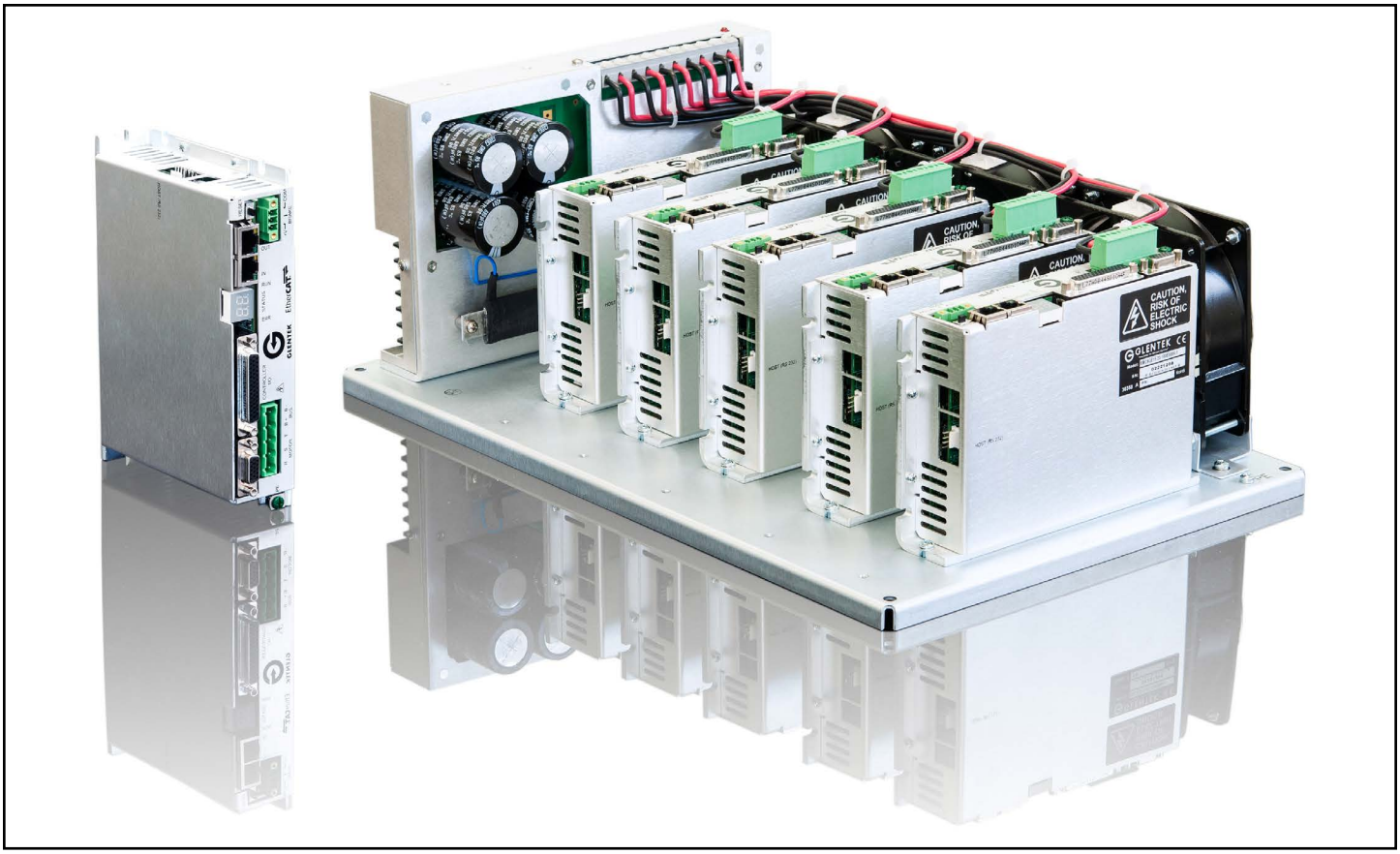
GLENTEK GAMMA SERIES DIGITAL PWM SERVO DRIVES
MODELS: SMB9GE & SMC9GE

Revision: 8/2/2023



Glentek's Gamma Series Digital PWM Servo Drives represents Glentek's latest offering of higher performance multi-core DSP control of brushless (standard servo and high-speed spindle), brush type, rotary, linear, voice coil, and AC induction motors. They offer expanded command and control modes, accept feedback from a wide range of devices and protocols, and include a programmable I/O. Both AC powered (stand alone and multi-axis) and DC powered (module) packages are available. These drives incorporate Field Oriented Control (FOC) and Space Vector Modulation (SVM) algorithms which provide optimum control that enable motors to run cooler and at higher velocities. Set-up, tuning, and system diagnostics are accomplished using MotionMaestro (Glentek's Windows-based software). There are two versions of this drive available, SMx9G16 models and SMx9GExx models (x's are model number placeholders). For information about SMx9G16 models, refer to the respective datasheet. Refer to the selection table below to select the version that best suits your application.

Model	9G16	9GE15	9GE30	9GE45	9GE75
Input Voltage (VDC)	24-710	24-565	-	-	-
Input Voltage (VAC)	110-500	110-400	110-240	110-240	110-240
Cont. Output Current (A)	5, 10, 15, 20, 25, 30, or 45	5, 10, 15, 20, 25, 30, or 45	30	45	75
Current Loop Bandwidth (kHz)	5	5	3 [1]	3 [1]	3 [1]
CANopen	•	•	•	•	•
EtherCAT		•	•	•	•
Safe Torque Off (STO)	•	•	• [2]	• [2]	• [2]
UL [3]	•				

Note:

[1] Higher current loop bandwidths may be available depending on the application.

[2] Safe Torque Off (STO) is available as an option for the indicated drives by special request only, and will have longer than normal lead times.

[3] The UL Recognized Component option is not available for every drive. Refer to the electrical ratings table for more details.

ELECTRICAL RATINGS

Model Number Code [3]	Input Voltage			Output Curent [1]			Available Package Configurations			Heatsink Type (Derating Factor) [2]
	VDC	VAC	Model Number Code [3]	Cont. A (A_{RMS})	Peak A (A_{RMS})	Model Number Code [3]	Module	Stand Alone	Multi-Axis	
15	24-60	N/A	0	5 (3.5)	10 (7.1)	1	•			L-Bracket (1)
15	24-60	N/A	0	10 (7.1)	20 (14.1)	3	•			L-Bracket (1)
15	24-60	N/A	0	15 (10.6)	30 (21.2)	4	•			L-Bracket (1)
15	24-60	N/A	0	20 (14.1)	40 (28.3)	5	•			L-Bracket (1)
15	24-60	N/A	0	25 (17.7)	50 (35.4)	6	•			L-Bracket (1)
15	24-60	N/A	0	30 (21.2)	60 (42.4)	7	•			L-Bracket (2)
15	24-60	N/A	0	45 (31.8)	80 (56.6)	8	•			L-Bracket (3)
15	60-190	110-130	1	5 (3.5)	10 (7.1)	1	•	•	•	L-Bracket (1)
15	60-190	110-130	1	10 (7.1)	20 (14.1)	3	•	•	•	L-Bracket (1)
15	60-190	110-130	1	15 (10.6)	30 (21.2)	4	•	•	•	L-Bracket (2)
15	60-190	110-130	1	20 (14.1)	40 (28.3)	5	•	•	•	Short Fin (2)
15	60-190	110-130	1	25 (17.7)	50 (35.4)	6	•	•	•	Short Fin (3)
15	190-370	208-240	2	5 (3.5)	10 (7.1)	1	•	•	•	L-Bracket (1)
15	190-370	208-240	2	10 (7.1)	20 (14.1)	3	•	•	•	L-Bracket (2)
15	190-370	208-240	2	15 (10.6)	30 (21.2)	4	•	•	•	L-Bracket (3)
15	190-370	208-240	2	20 (14.1)	40 (28.3)	5	•	•	•	Short Fin (3)
15	190-370	208-240	2	25 (17.7)	50 (35.4)	6	•	•	•	Short Fin (4)
15	370-565	360-400	3	5 (3.5)	10 (7.1)	1	•	•	•	L-Bracket (2)
15	370-565	360-400	3	10 (7.1)	20 (14.1)	3	•	•	•	Short Fin (2)
15	370-565	360-400	3	15 (10.6)	30 (21.2)	4	•	•	•	Short Fin (3)
15	370-565	360-400	3	20 (14.1)	40 (28.3)	5	•	•	•	Long Fin (3)
15	370-565	360-400	3	25 (17.7)	50 (35.4)	6	•	•	•	Long Fin (4)
30	N/A	110-130	1	30 (21.2)	60 (42.4)	7		•		Long Fin (2)
30	N/A	208-240	2	30 (21.2)	60 (42.4)	7		•		Long Fin (3)
45	N/A	110-130	1	45 (31.8)	80 (56.6)	8		•		Long Fin (2)
45	N/A	208-240	2	45 (31.8)	80 (56.6)	8		•		Long Fin (3)
75	N/A	110-130	1	75 (53)	120 (84.9)	9		•		Long Fin (3)
75	N/A	208-240	2	75 (53)	120 (84.9)	9		•		Long Fin (4)

Notes:

[1] The column Cont. Output Current is the continuous current and the column Peak Output Current is the intermittent peak current. For output current ratings in brushless mode, ratings for each model are listed as peak of the sine wave phase current values followed by the equivalent RMS phase current values (in parentheses). In brush or voicecoil mode, A is the current, and the RMS values (in parentheses) can be ignored. All output current ratings are for three-phase VAC inputs or VDC inputs. If a single-phase VAC input is used, the total output current for all axes is limited to a maximum of 15 A cont. / 30 A peak.

[2] Three heatsink types (L-Bracket, Short Fin, and Long Fin) are available depending on the input voltage and output current. For dimensions, refer to pgs. 6-23. There are 4 standard categories for ambient operating temperature and current derating denoted by the number following the heatsink type. All categories require forced air cooling.

Category 1: 0 to 60 °C without derating. Derate current 10% per °C over 60 °C.
Category 2: 0 to 50 °C without derating. Derate current 5% per °C over 50 °C.
Category 3: 0 to 40 °C without derating. Derate current 3% per °C over 40 °C.
Category 4: 0 to 30 °C without derating. Derate current 2.5% per °C over 30 °C.
Special: Contact Glentek for models with a lower operating temperature limit of -40 °C.

[3] Model Codes are used on pgs. 24-26 for model numbering

[5] Bus power logic (SMB models) not available for input voltages of greater than 370 VDC (Module) or 360 VAC (Stand Alone and Multi-Axis).

FEATURES

Command/Control Modes
EtherCAT
CANopen
+/-10 VDC for current (torque) or velocity (RPM)
Pulse (step) and direction
Encoder follower
CW/CCW (up/down mode)
External sine commutation (2-phase current mode)
RS-232 & RS-485
PWM for current (torque) or velocity (RPM) in 50% duty cycle format (one-wire) or 100% duty cycle format (two-wire)
Indexer/Point-to-Point
Camming/Gearing

Feedback
Incremental quadrature encoder
Digital Hall sensors or commutation tracks from encoder
Absolute serial encoder (BiSS, EnDat, and T-Format)
Analog Sin/Cos encoder
Resolver
Analog tachometer

I/O		
Dedicated Digital I/O	Inputs:	2 STO optically isolated
	Output:	Brake (max 2 A @ 24 VDC)
Programmable Digital I/O	Inputs:	5 optically isolated, 6 Schmitt trigger, 2 differential
	Outputs:	3 MOSFETS (max 1.5A, 24 VDC), 2 optically isolated (max 10 mA, 24 VDC), relay (max 2 A, 30 VDC)
Analog I/O	Inputs:	2 differential (16 bit A/D)
	Outputs:	2 single ended, programmable (12 bit A/D)

Safety Disable
Safe Torque Off (STO) in accordance with IEC61800-5-2 (available upon request only)

Environmental Conditions	
Storage Temperature:	-40°C to 80°C
Ambient Operating Temperature:	Refer to the electrical ratings table
Humidity:	5% to 95% relative humidity, non-condensing
Altitude:	Up to 1000m without derating, derate current 10% per 1000m above 1000m

FEATURES

Performance	
FOC	All Gamma Series employ Field Oriented Control method which allows accurate control in both steady state or transient operation, and optimal orientation of the magnetic field.
Space Vector Modulation	Glentek's advanced algorithms allow for maximum utilization of the DC bus voltage while generating minimum harmonic distortion of the currents in the winding of 3-phase AC motor.
Digital current loops	Current loop bandwidths up to 5 kHz.
Digitally tuned	All parameters set digitally. No potentiometers to adjust. DSP control for the ultimate in high performance.
Parametric filtering	Provides control engineers advanced filtering to eliminate unwanted system mechanical resonance.
Smart-Comm Initialization	Eliminates the need for Hall sensor or commutation tracks for many applications.
Auto Phase Finding	Plug and Play for all types of three phase brushless motors. The drives algorithm will automatically find and align the motor phases.
Auto Phase Advance	Glentek's advanced algorithms incorporated in the Gamma Series drives, automatically provide phase advance, insuring that the current is delivered at the appropriate time, and provides the most efficient operation.
Sinusoidal commutation	For the ultimate in efficiency and smooth motion. Commutates from almost any resolution linear or rotary encoder or Hall sensors only.
Fault protection	Short from output to output, short from output to ground, drive RMS over current, drive under/over voltage, drive over temperature, motor over temperature.
On-the-fly mode switching	This feature allows the drive to switch between any mode of operation on-the-fly.
Software configurable	Glentek's Windows™ based MotionMaestro© software provides ease of set-up, monitoring and tuning with no previous programming experience required. This software is Windows™ 95/98/2000/XP, NT, Vista, 7, 8, and10 compatible.
Silent operation	25 kHz PWM standard.
Command/control Modes	EtherCAT, CANopen, +/-10V for current (torque) or velocity (RPM), pulse (step) and direction, encoder follower, external sine commutation (2-phase current mode), RS-232, RS-485, PWM for current (torque) or velocity (RPM), camming/gearing, Indexer/Point-to-Point.
Regulatory	
CE marked	All servo drives are CE marked in accordance with EN60204-1 (IEC204-1).
RoHS compliant	All servo drives are RoHS compliant.
Connectivity	
EtherCAT	CANopen over EtherCAT, the drive device profile is based on IEC 61800-7-201 (CiA 402).
CANopen	High-speed (up to 1 Mbits/s) CAN interface for communications between nodes in real-time control applications. The drive device profile is based on IEC 61800-7-301/201 (CiA 402).
RS-232 or RS-485	High speed (115.2K baud) serial communication interface for setup and tuning and diagnostics. Note: RS-485 is optional.
Feedback	
Encoder feedback	Accepts quadrature encoder signals up to 5 MHz (maximum frequency of up to 10 MHz is possible, but is system dependent). Absolute serial encoder (Biss, EnDat, and T-Format). Analog Sin/Cos encoder.
Encoder Output Divider	The encoder input signal can be divided by a user selectable integer for the encoder output signal. Note: Available upon request only.
Resolver Feedback	The drive creates a simulated encoder output with a typical resolution of 12 bits.
Tachometer feedback	Accepts analog signals from all types of tachometer feedback.
I/O	
Programmable Functions	Analog signal command, +/- limits, inhibit/enable, fault, reset, motor temperature, encoder and step & direction.
Input	
Wide operating voltage	24-565 VDC for drive modules. Stand alone and multi axis versions can be ordered for operation from either 110-130 VAC, 208-240 VAC, and 360-400 VAC main lines (single or 3-phase, 50/60 Hz). Note: Non-standard voltages can be ordered upon request.
Direct AC operation	The stand-alone units and multi-axis chassis include DC bus power supplies, cooling fans and a regen clamp with dissipation resistor.
External logic supply	24-48 VDC, 600mA max @ 24 VDC powers all logic & encoder. This works as a "keep alive" for drives.
Build	
Complete isolation	Complete isolation between signal and power stage.
Non-volatile memory	All parameters are stored in non-volatile memory for reliable start up. Note: Available upon request, up to 16 different configurations can be stored in the drives's non-volatile memory.
Relay outputs	Two pins provide an interface for the relay. They turn on when a desired condition occurs.
Status indicator	Two 8-segment displays indicates drive status and diagnostics.
SMT construction	Provides ultra compact size, cost competitive package and high reliability.

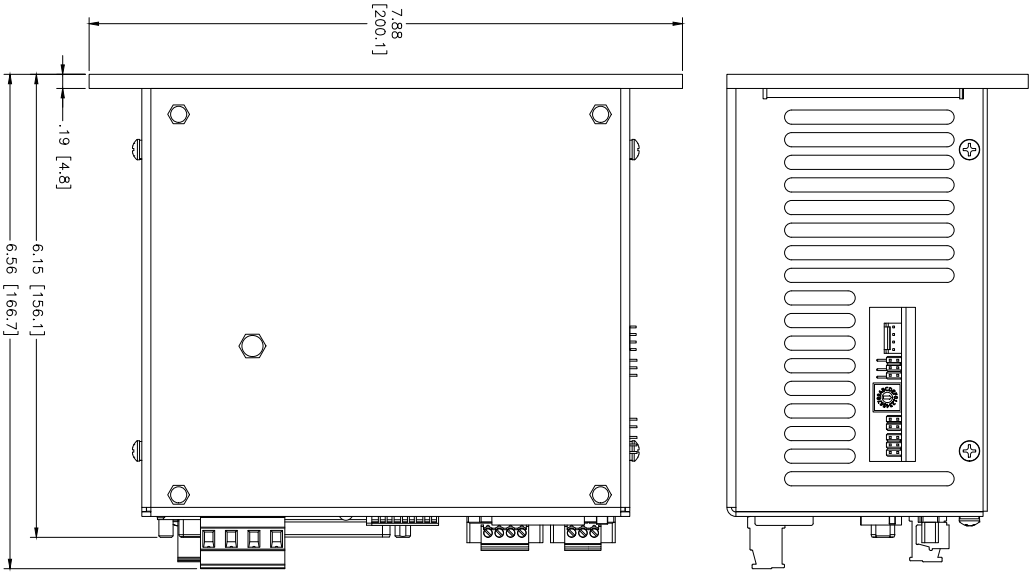
Package Configuration Selection Table

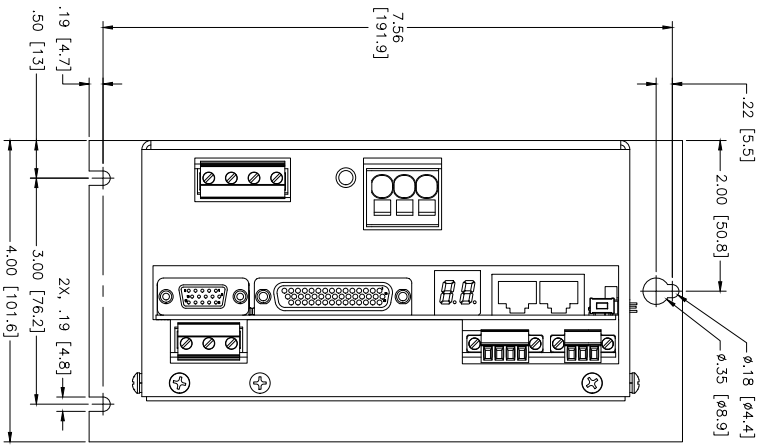
Glentek offers three different types of packages: stand alone, module, and multi-axis. Stand alone and multi-axis packages require an AC input and are available in three configurations: A, B, and F. These codes are used in the model numbering. Modules are typically used for cost sensitive applications where the customer provides DC bus power supply, forced-air cooling, and regen clamp. The table below specifies the differences between the various package configurations. Custom configurations are available upon request.

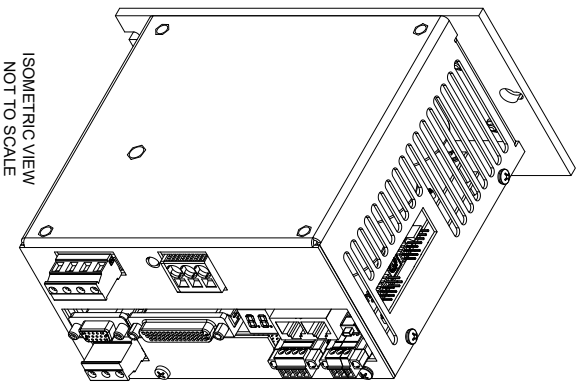
Feature	Stand Alone: A	Stand Alone: B	Stand Alone: F	Module	Multi-Axis: A	Multi-Axis: B
Drive(s)	1	1	1	1	1-5	1-5
DC Bus Power Supply	•	•	•		•	•
In-rush current limiting at power on	•	•	•		•	•
Regen Clamp	•		•		•	
Dissipation Resistor	•				•	
Fan(s)	•	•			•	•
Fuses					•	•

SMB/SMC9GE15-1F Stand Alone (L-Bracket)

9GE15-1F STANDALONE : L-BRACKET HEATSINK







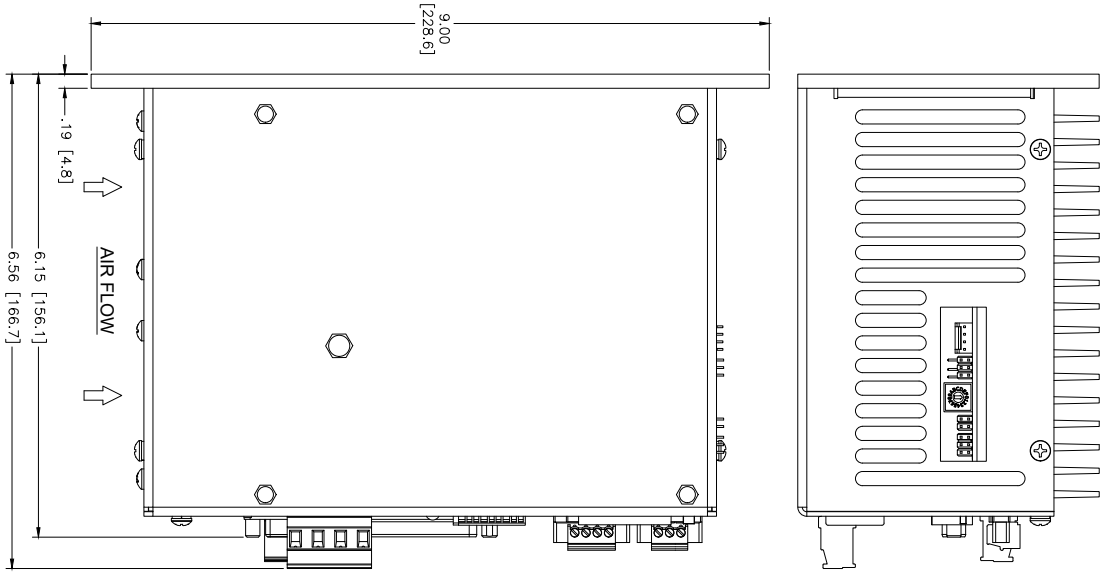
ISOMETRIC VIEW
NOT TO SCALE

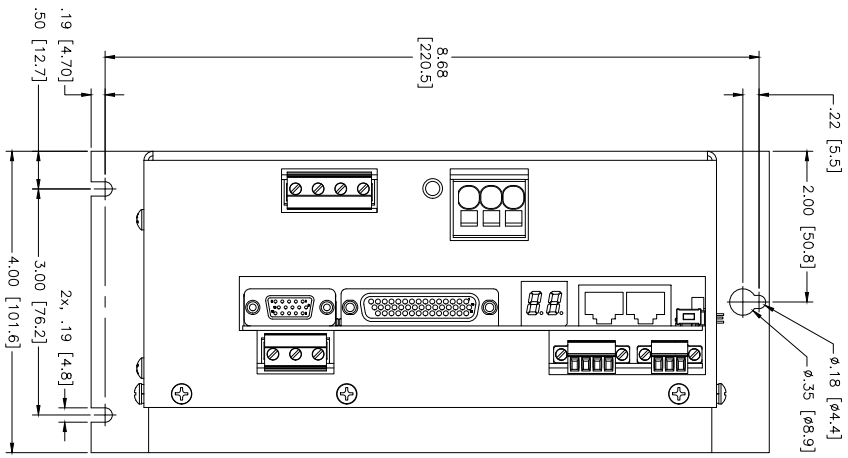
DRAWING # 9GE15-1010-010 | SCALE: .875:1 | DRAWN BY: M. TAGUPA | DATE: 22MAR22

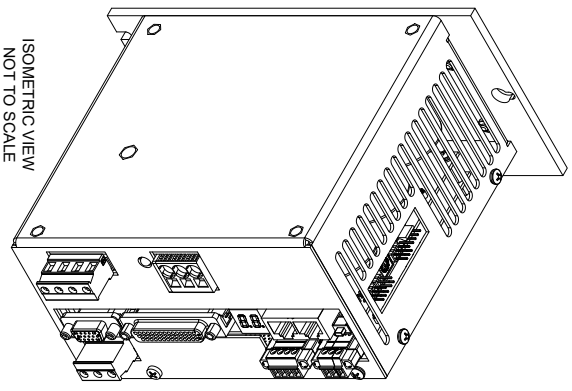
UNLESS OTHERWISE SPECIFIED
DIMENSIONS ARE IN INCHES

TOLERANCES
AS FOLLOWS:
DECIMAL: .XX = ±0.01
.XXX = ±0.005
ANGULAR < = ±0.5°

SMB/SMC9GE15-1A/1B Stand Alone (Short Fin)







9GE15-1A/1B STANDALONE : SHORT FIN HEATSINK

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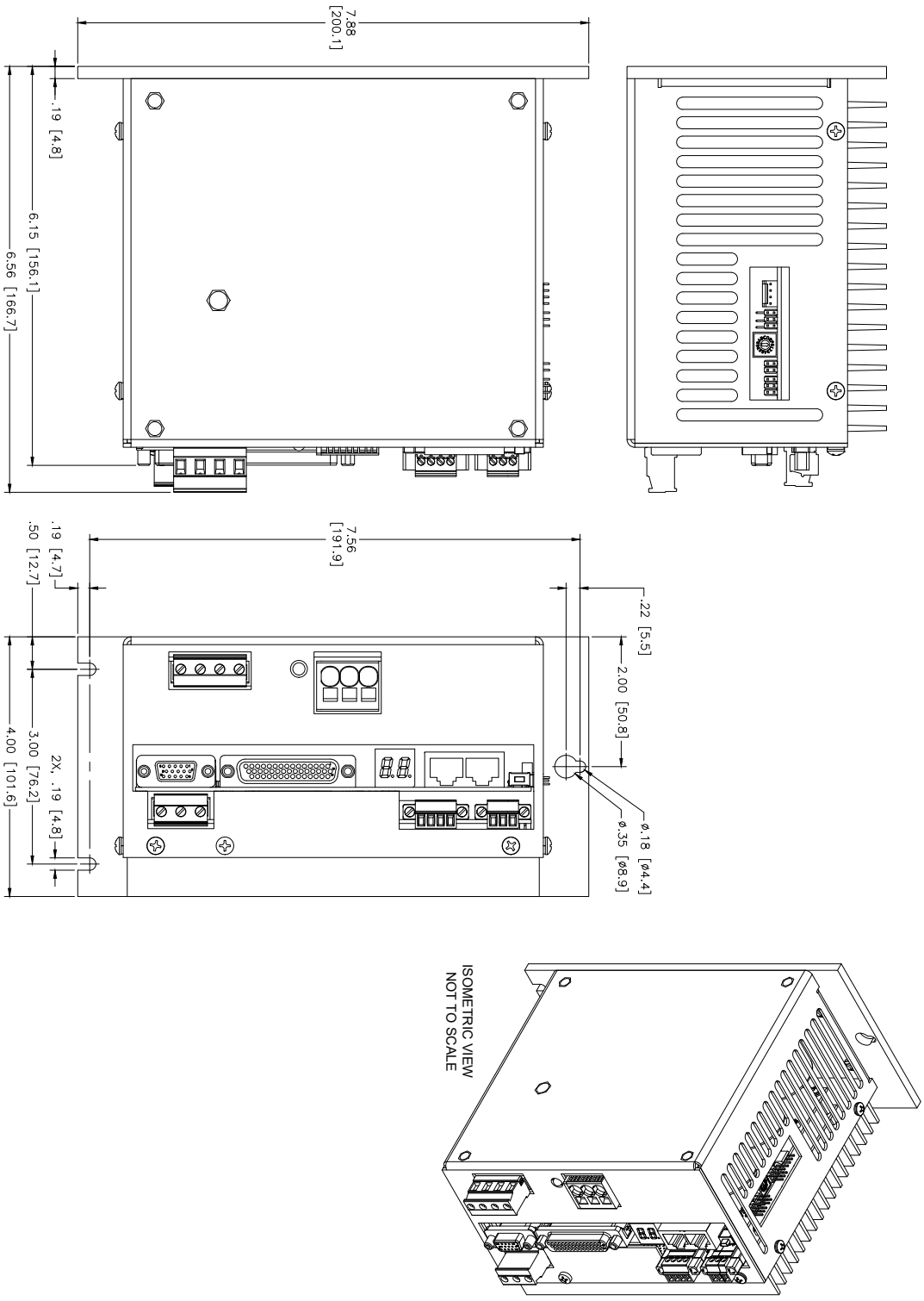
UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES

TOLERANCES AS FOLLOWS: DECIMAL: .XX = ±0.01 .XXX = ±0.005 ANGULAR < = ±0.5°

SMB/SMC9GE15-1F Stand Alone (Short Fin)



9GE15-1F STANDALONE : SHORT FIN HEATSINK

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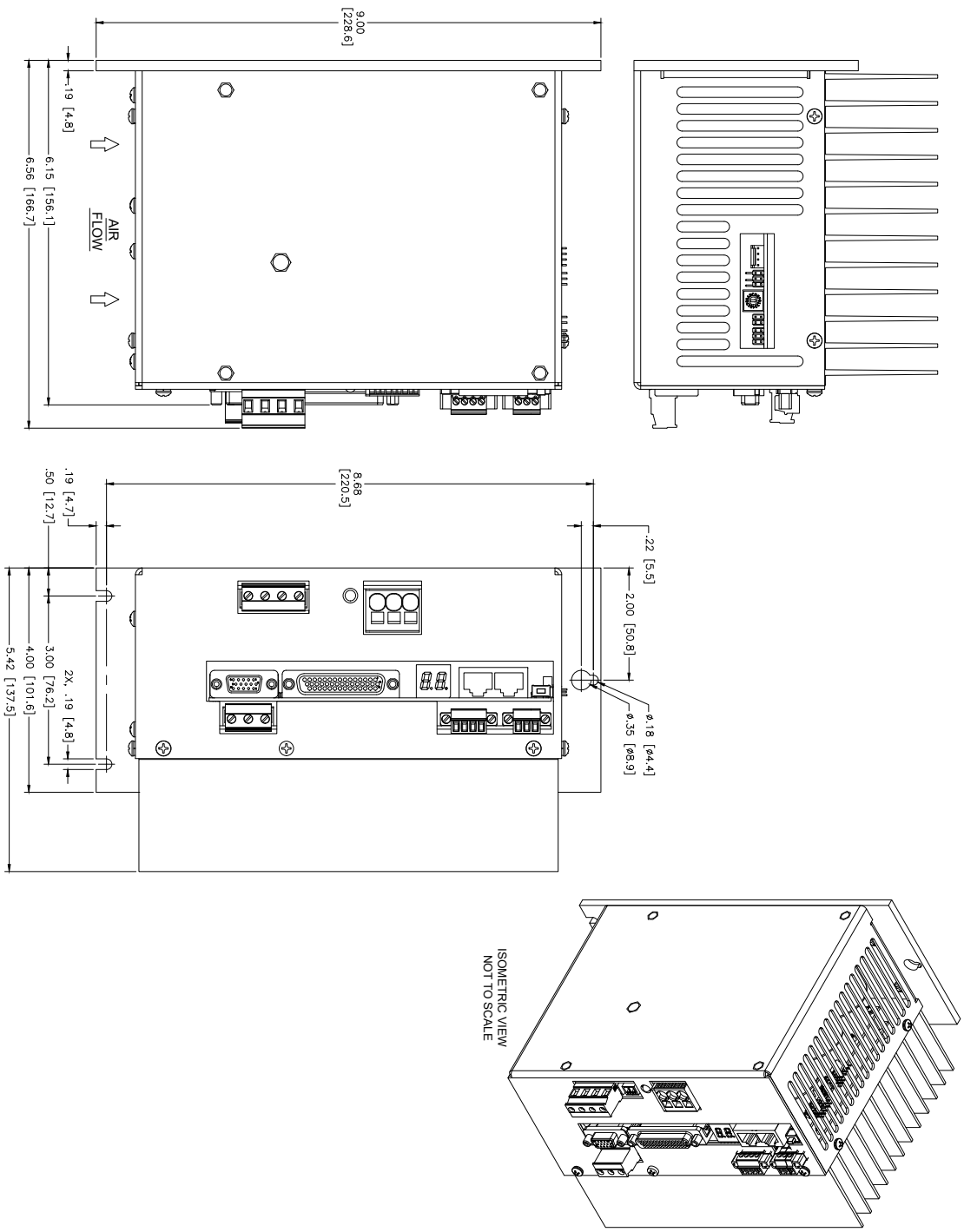
UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES

TOLERANCES AS FOLLOWS: DECIMAL: .XX = ±0.01 .XXX = ±0.005 ANGULAR < = ±0.5°

SMB/SMC9GE15-1A/1B Stand Alone (Long Fin)



9GE15-1A/1B STANDALONE : LONG FIN HEATSINK

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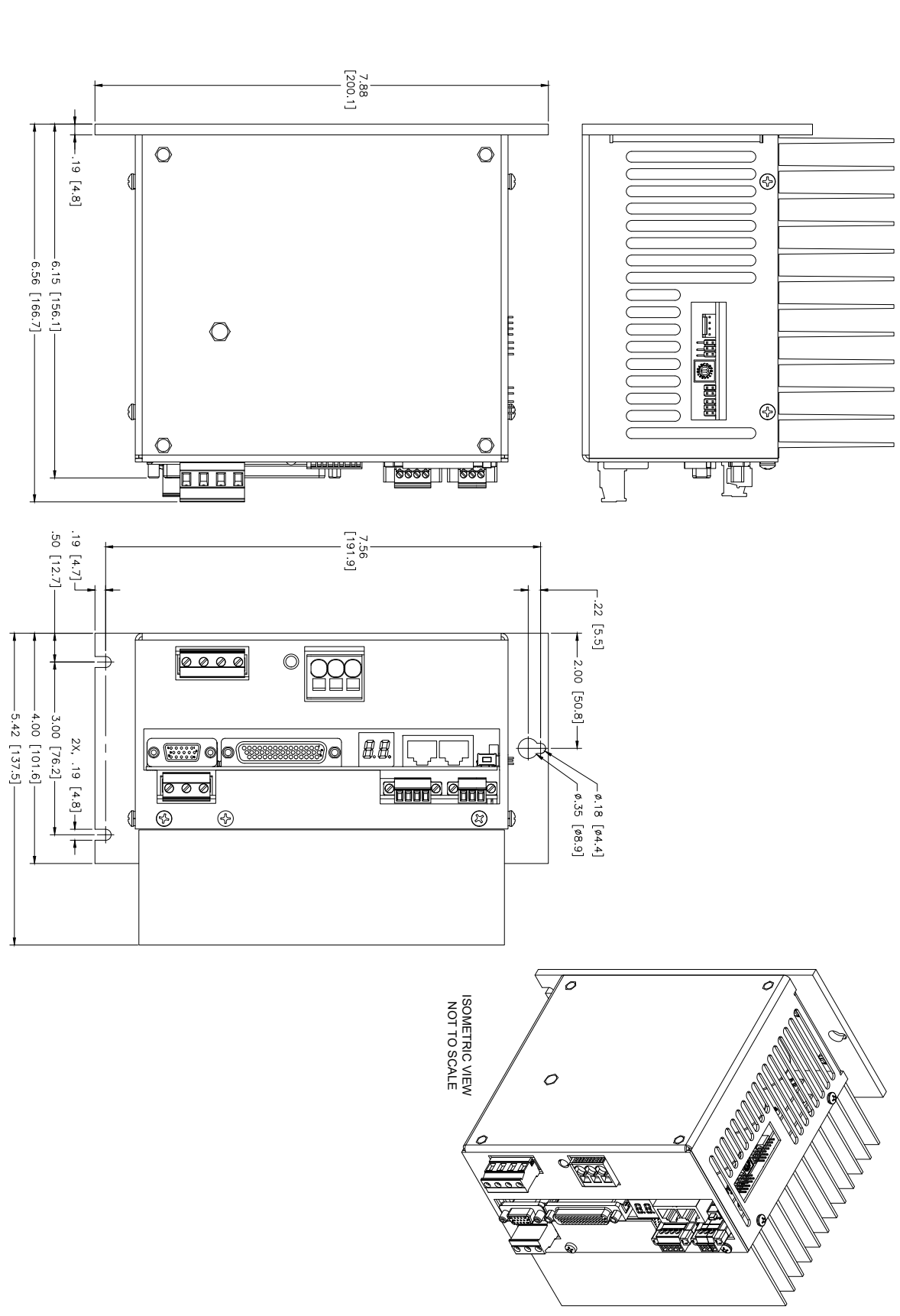
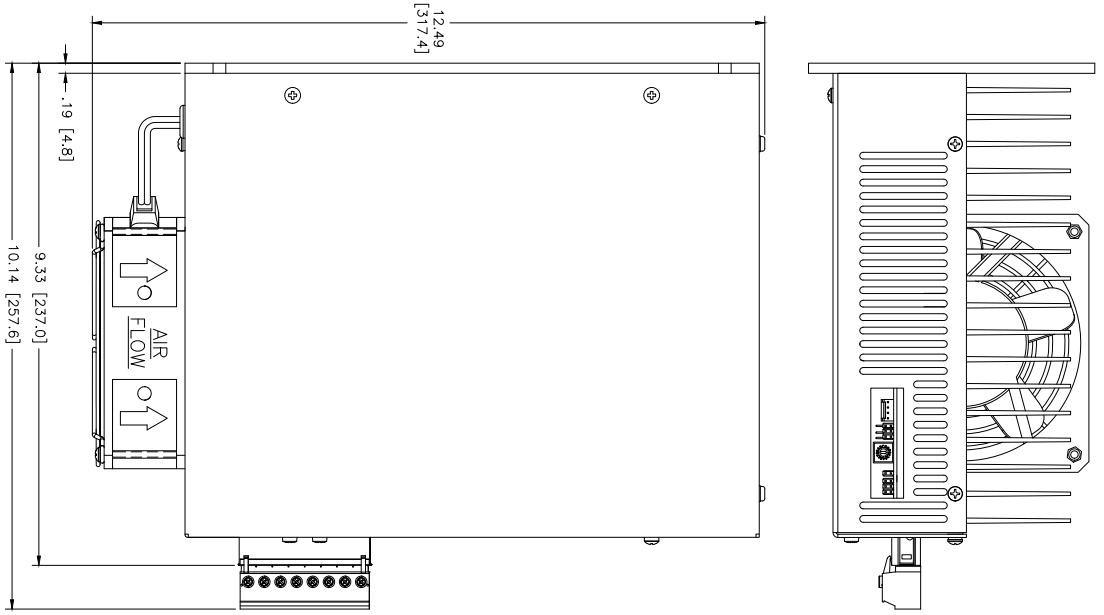
UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES

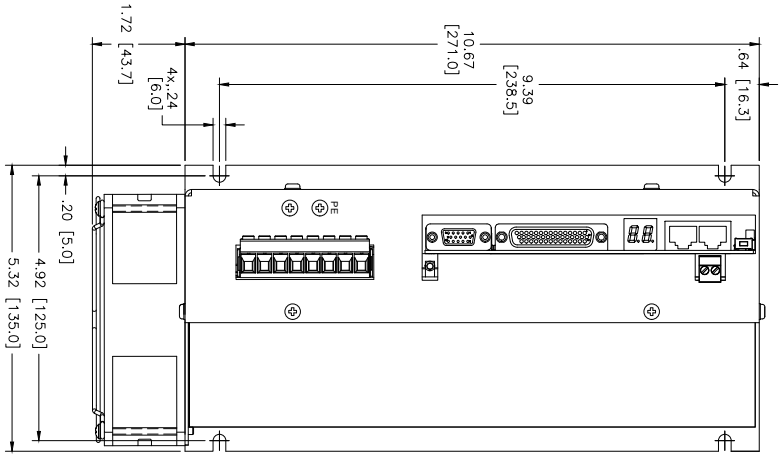
TOLERANCES AS FOLLOWS: DECIMAL: .XX = ±0.01 .XXX = ±0.005 ANGULAR < = ±0.5°

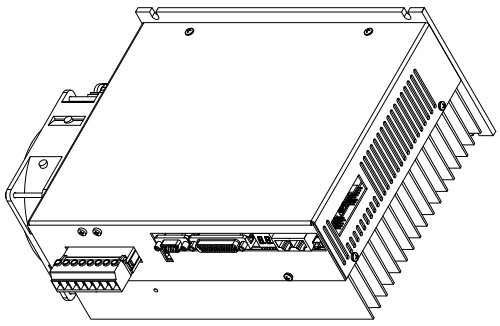
SMB/SMC9GE15-1F Stand Alone (Long Fin)



SMB/SMC9GE30-1A Stand Alone (Long Fin)







ISOMETRIC VIEW
NOT TO SCALE

9GE30-1A STANDALONE : LONG FIN HEATSINK

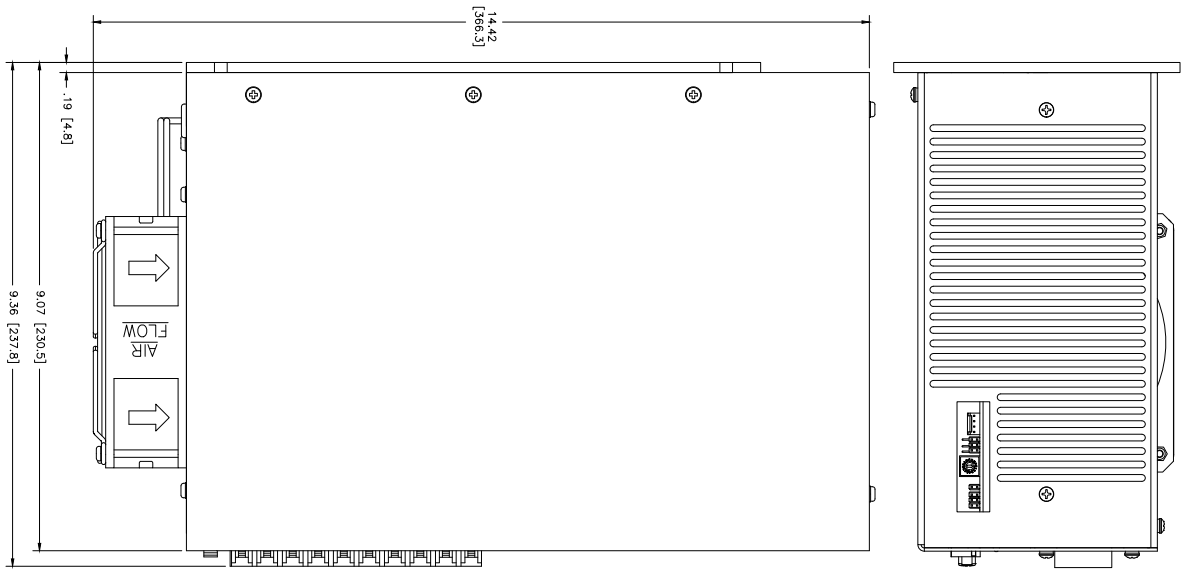
DRAWING # 9GE15-1010-015 | SCALE: .625:1 | DRAWN BY: M. TAGUPA | DATE: 21MAR22

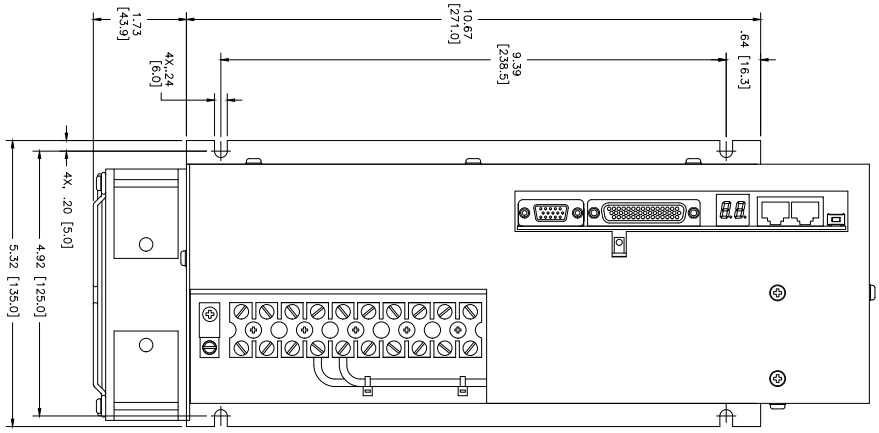
UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES

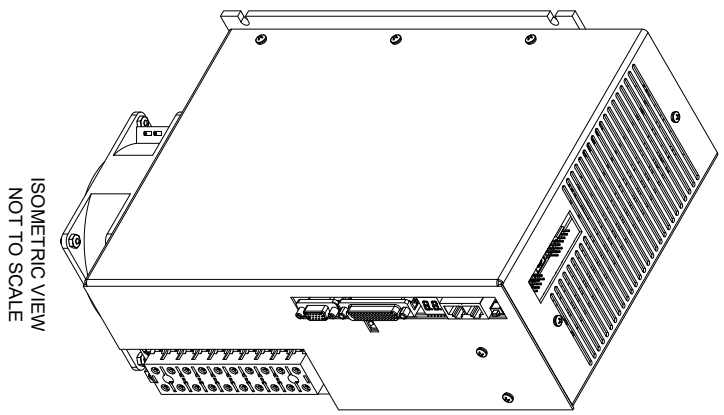
TOLERANCES AS FOLLOWS: DECIMAL: .XX = ±0.01 .XXX = ±0.005 ANGULAR < = ±0.5°

SMB/SMC9GE45-1A Stand Alone (Long Fin)

9GE45-1A STANDALONE : LONG FIN HEATSINK







ISOMETRIC VIEW
NOT TO SCALE

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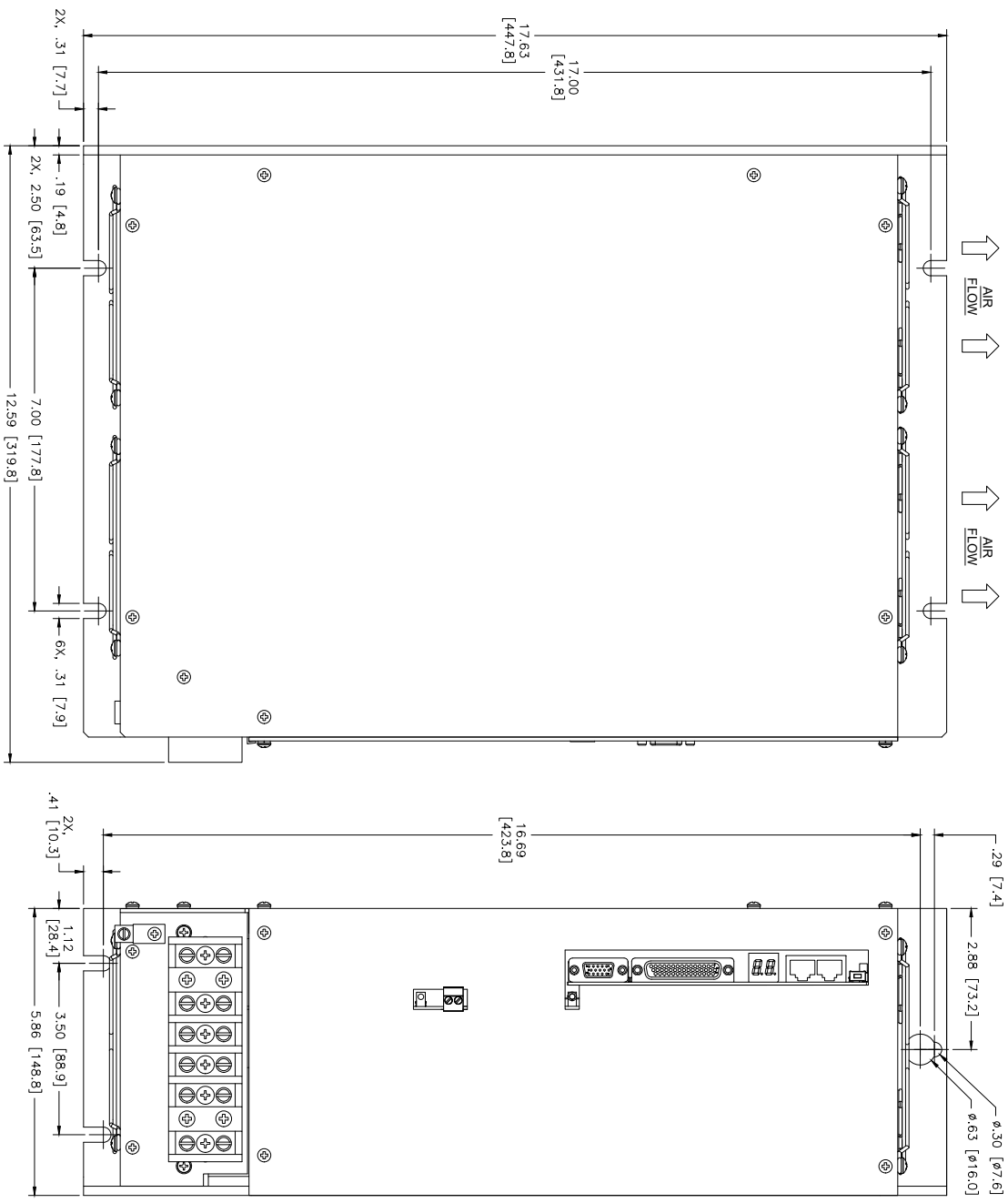
UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES

TOLERANCES AS FOLLOWS: DECIMAL: .XX = ±0.01 .XXX = ±0.005 ANGULAR < = ±0.5°

SMB/SMC9GE75-1A Stand Alone (Long Fin)

9GE75-1A STANDALONE : LONG FIN HEATSINK



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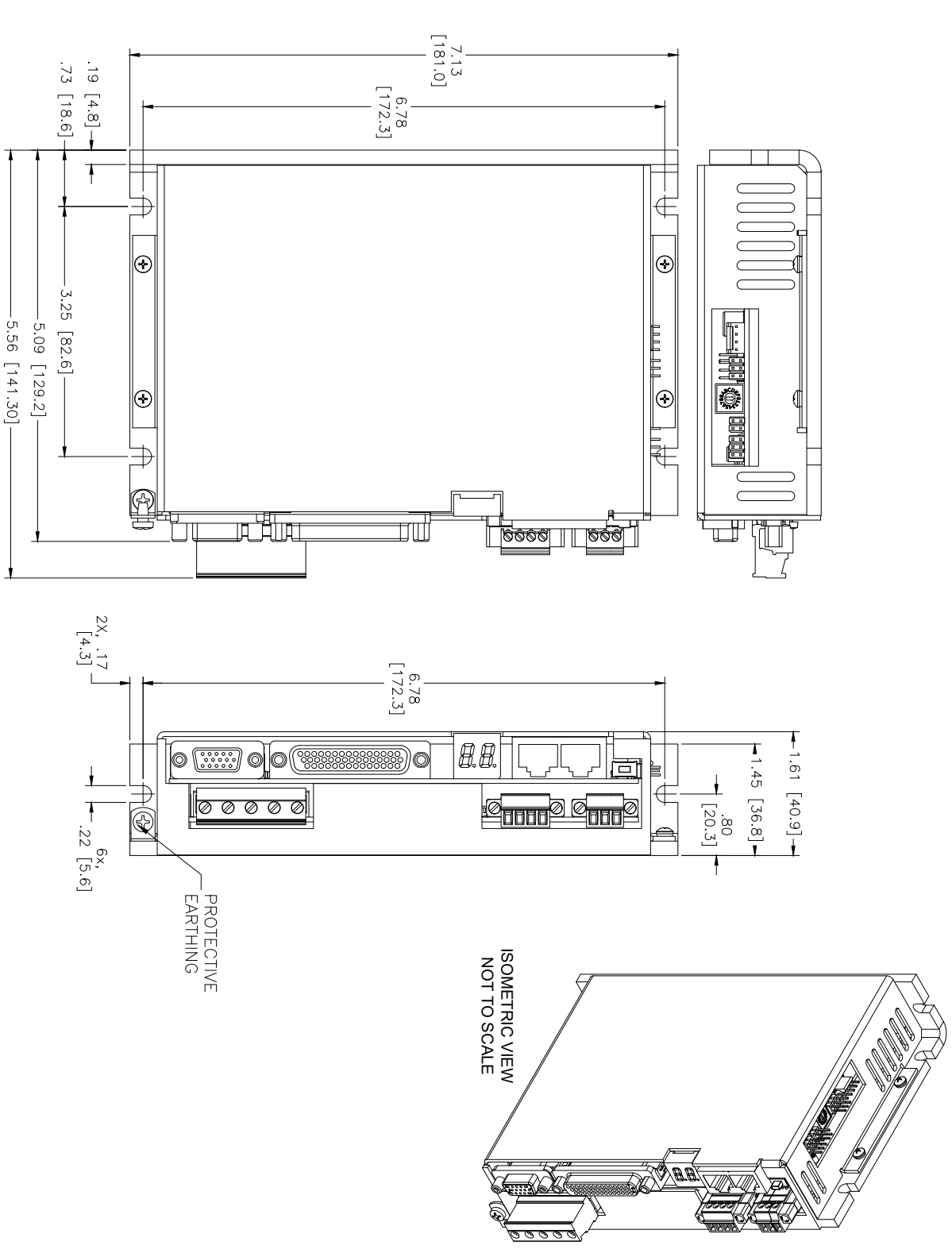
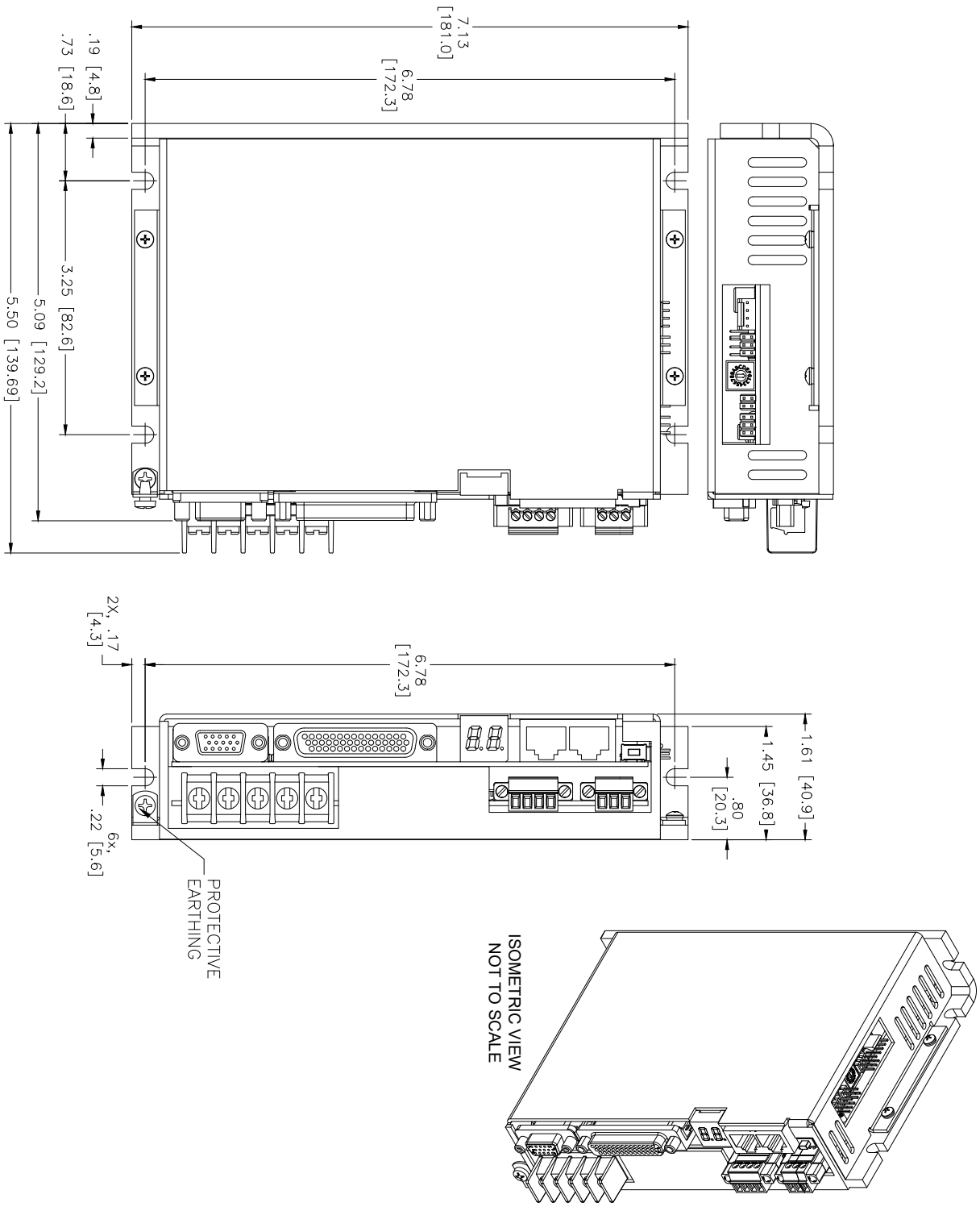
UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES

TOLERANCES AS FOLLOWS: DECIMAL: .XX = ±0.01 .XXX = ±0.005 ANGULAR < = ±0.5°

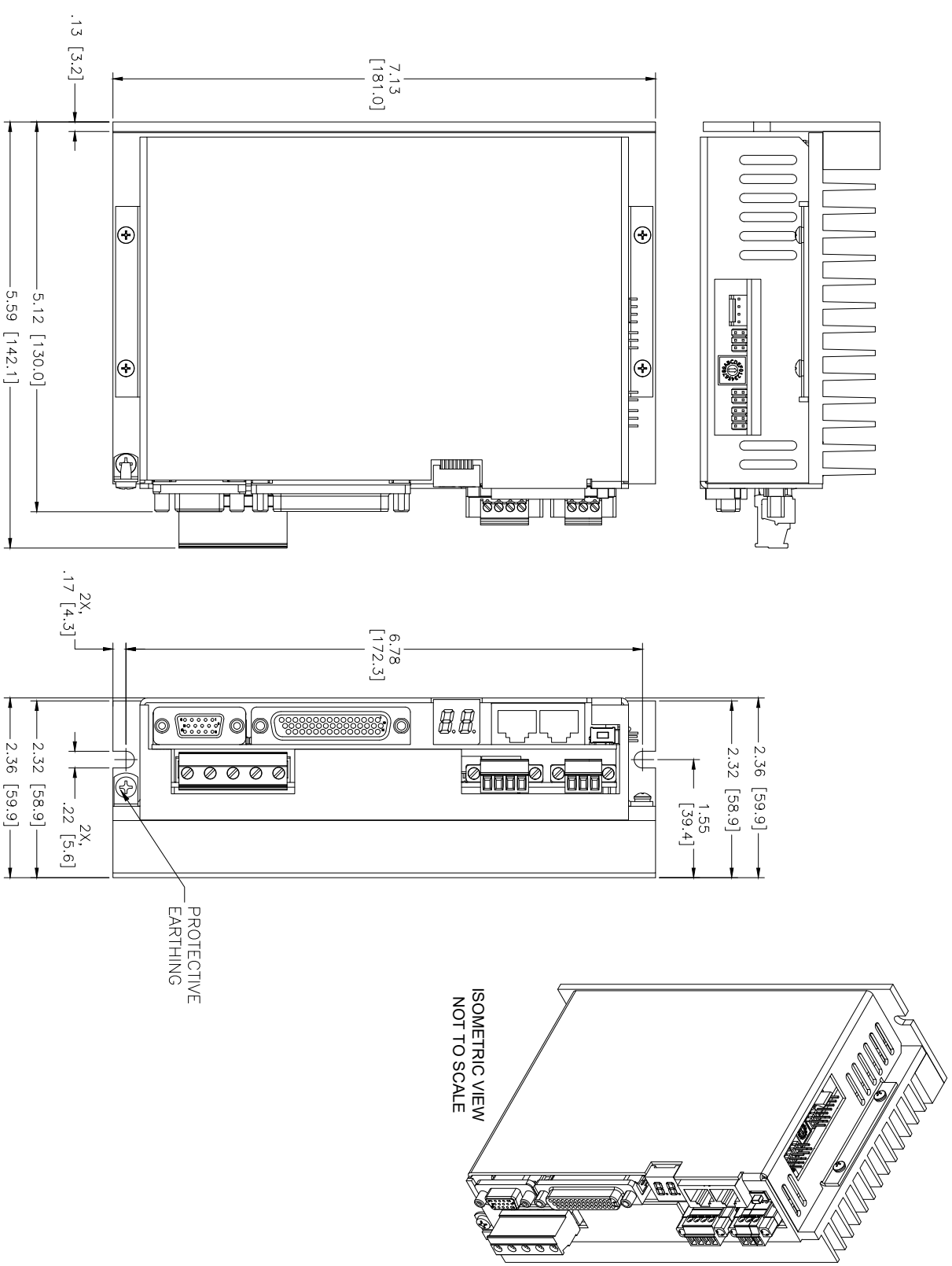
SMB/SMC9GE15 Module (L-Bracket)



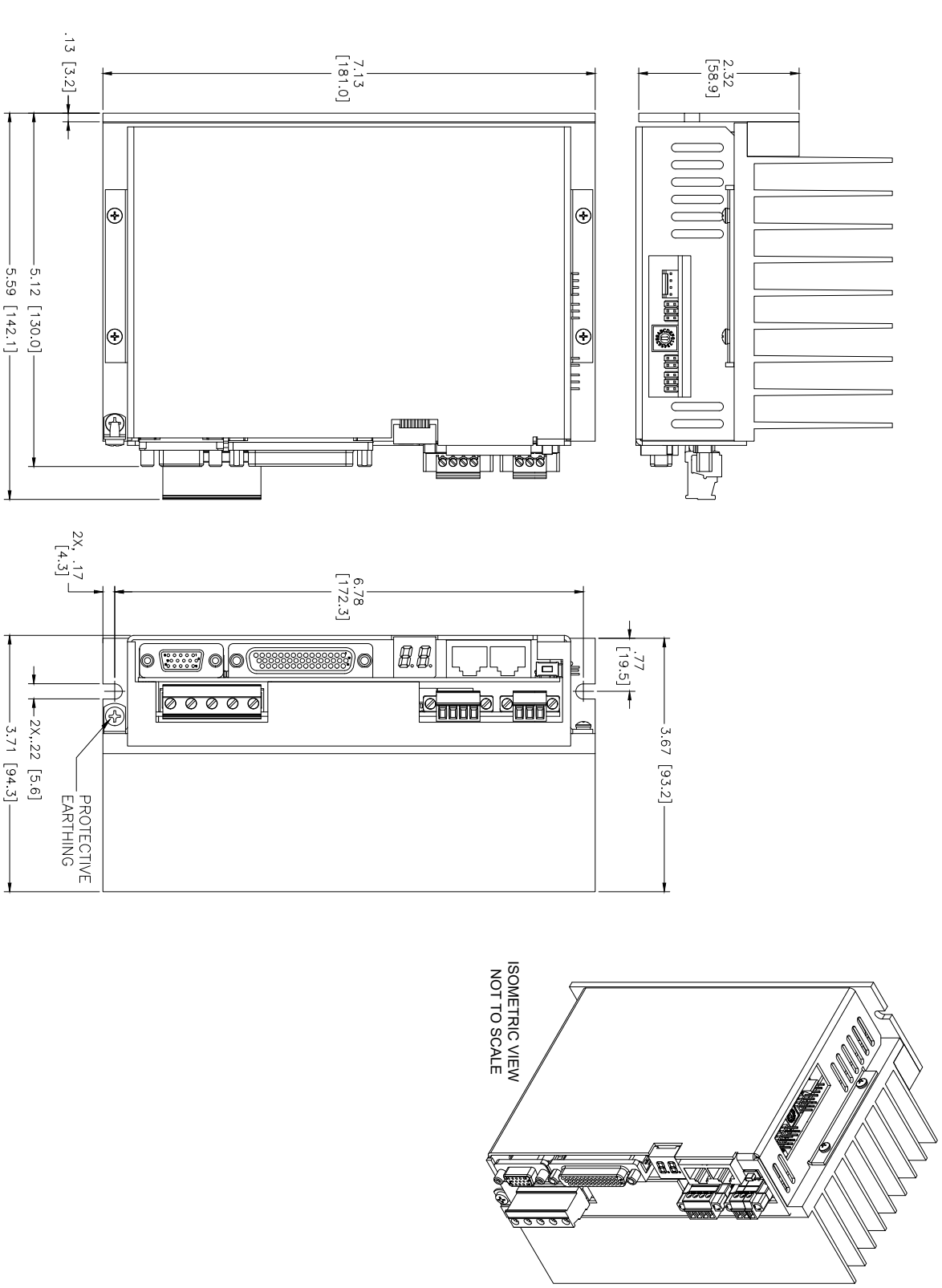
SMB/SMC9GE15 Module (30 A and 45 A) (L-Bracket)



SMB/SMC9GE15 Module (Short Fin)

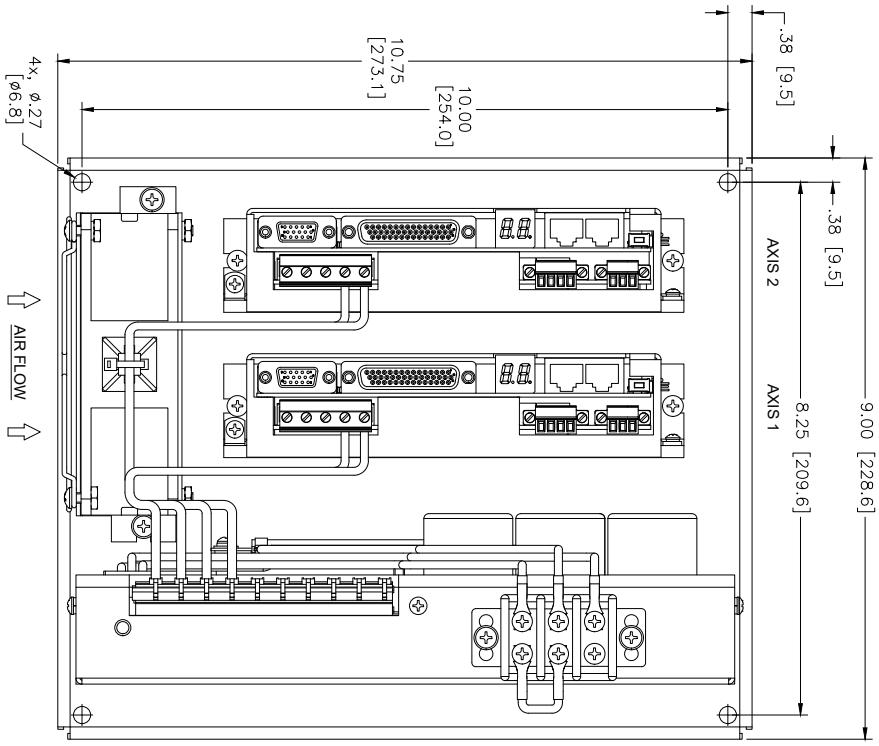


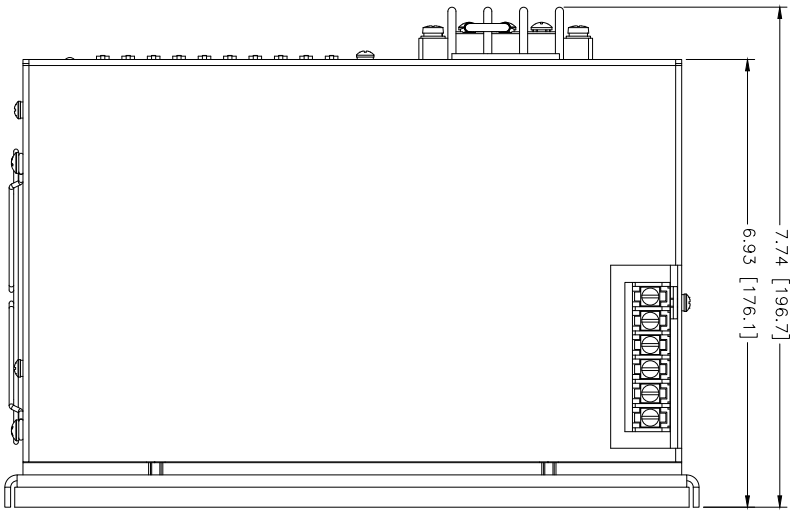
SMB/SMC9GE15 Module (Long Fin)

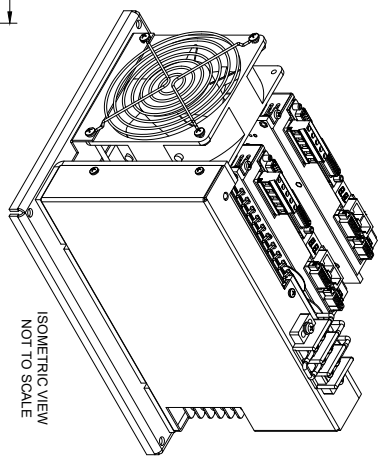


SMB/SMC9GE15 2-Axis Package (L-Bracket)

9GE15 2-AXIS PACKAGE: L-BRACKET MODULES





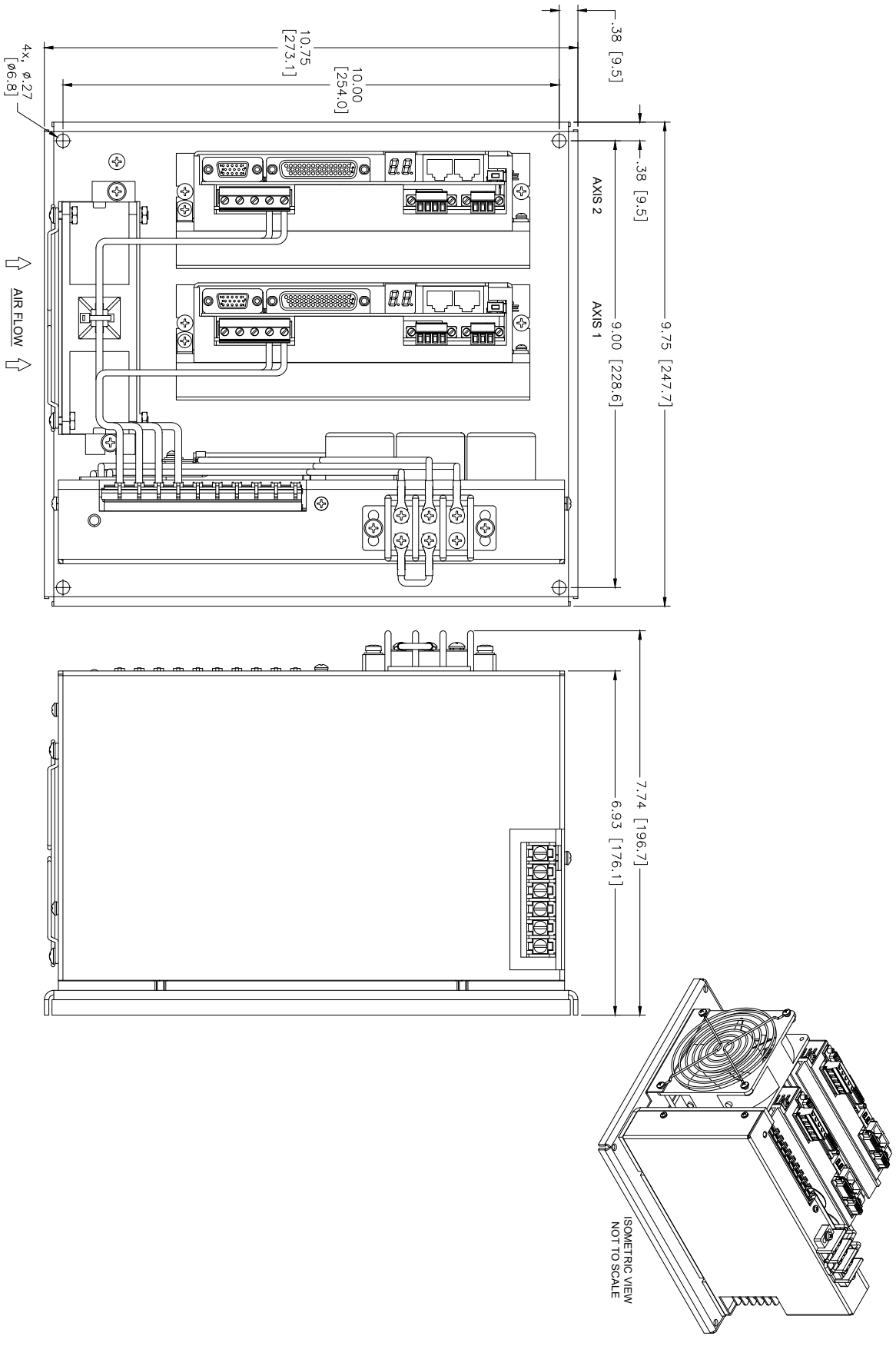


DRAWING # 9GE15-1010-004 | SCALE: .75:1 | DRAWN BY: M. TAGUPA | DATE: 17MAR22

UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES

TOLERANCES AS FOLLOWS: DECIMAL: .XX = ±0.01 .XXX = ±0.005 ANGULAR < = ±0.5°

SMB/SMC9GE15 2-Axis Package (Short Fin)



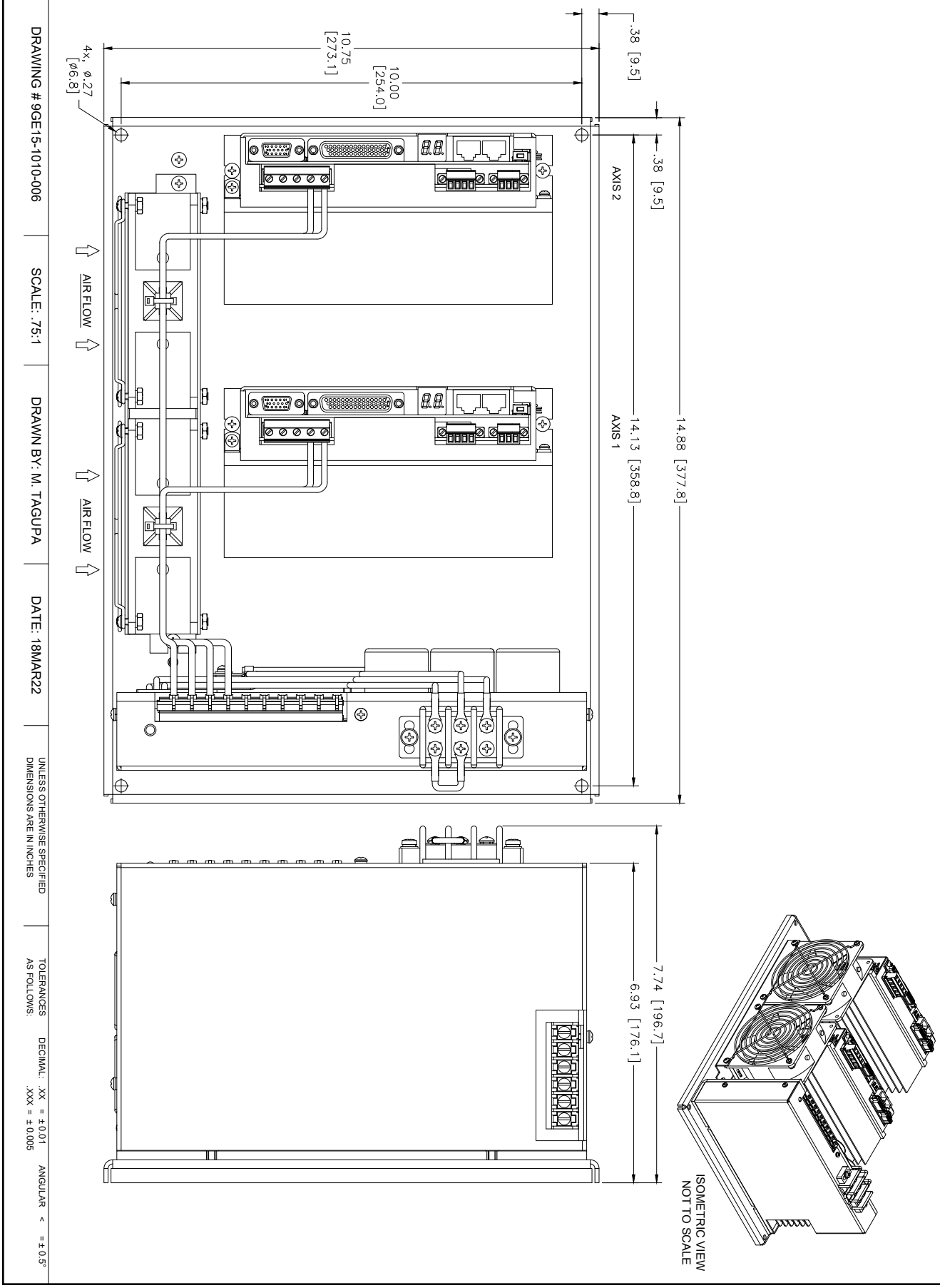
9GE15 2-AXIS PACKAGE: SHORT FIN MODULES

DRAWING # 9GE15-1010-005 | SCALE: .75:1 | DRAWN BY: M. TAGUPA | DATE: 18MAR22

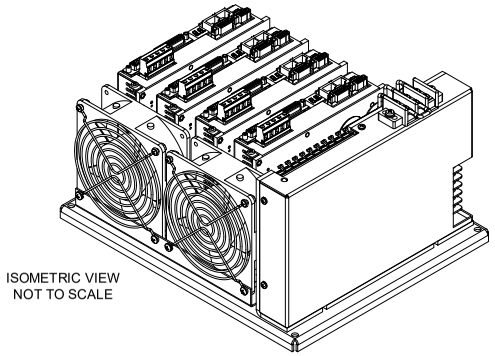
UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES

TOLERANCES AS FOLLOWS: DECIMAL: .XX = ±0.01 .XXX = ±0.005 ANGULAR < = ±0.5°

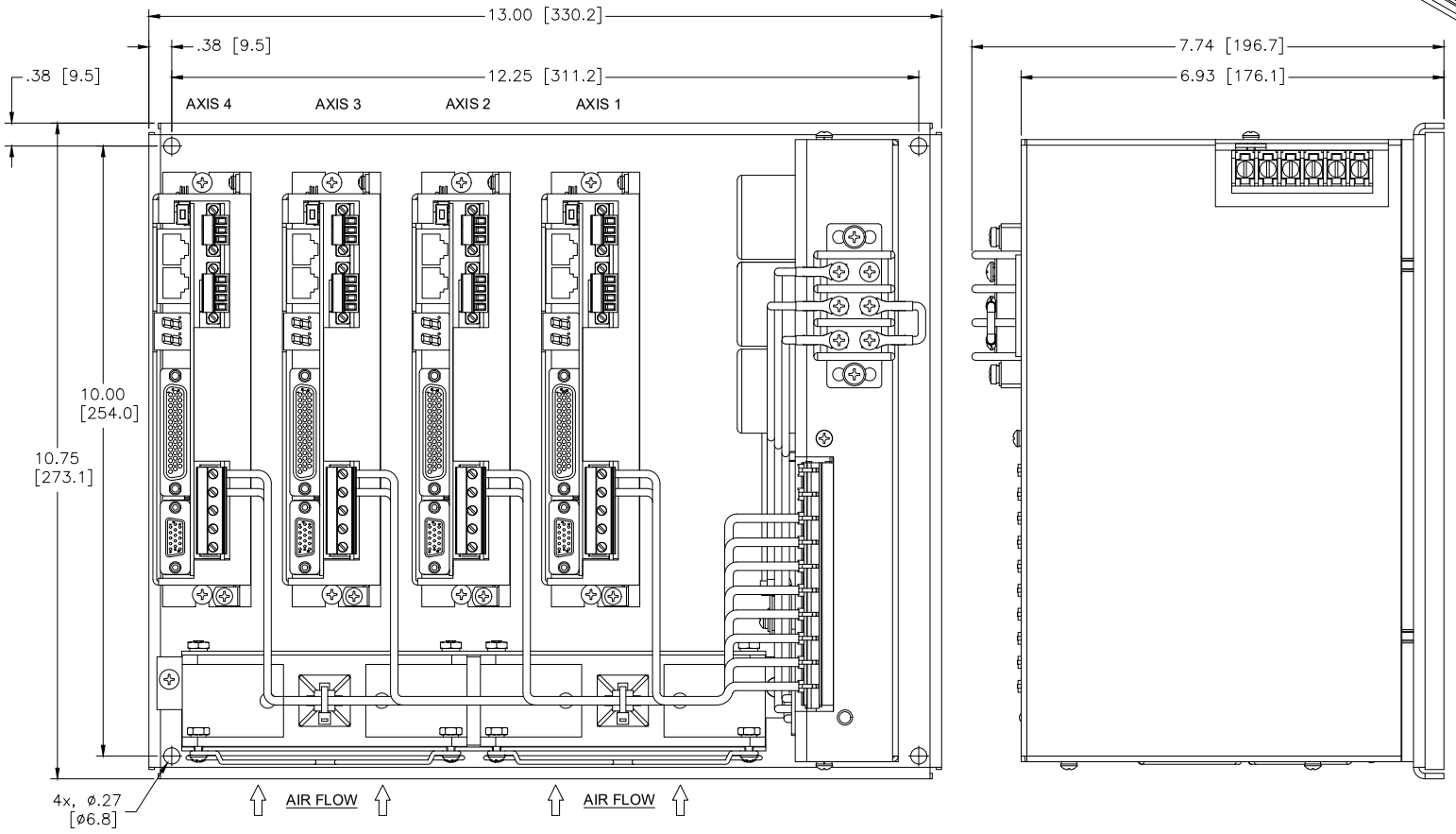
SMB/SMC9GE15 2-Axis Package (Long Fin)



9GE15 4-AXIS PACKAGE: L-BRACKET MODULES



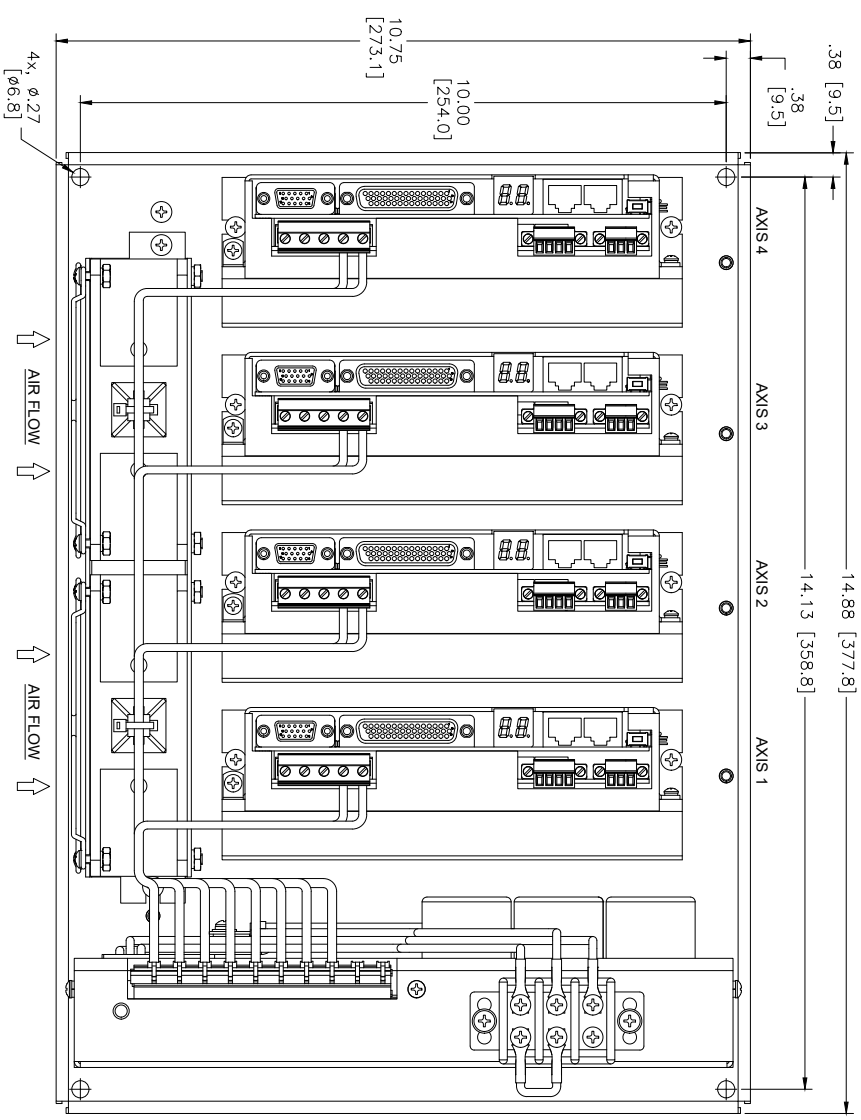
ISOMETRIC VIEW
NOT TO SCALE

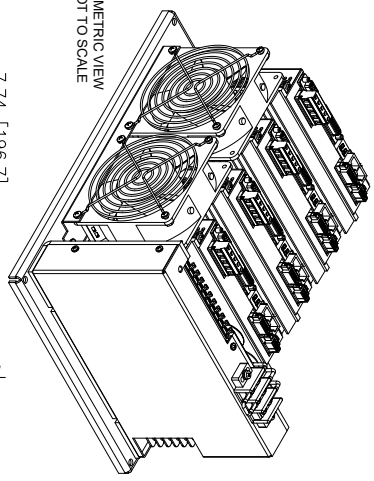


DRAWING # 9GE15-1010-007	SCALE: .75:1	DRAWN BY: M. TAGUPA	DATE: 18MAR22	UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES	TOLERANCES AS FOLLOWS: DECIMAL: .XX = ± 0.01 .XXX = ± 0.005 ANGULAR < = ± 0.5°

SMB/SMC9GE15 4-Axis Package (Short Fin)

9GE15 4-AXIS PACKAGE: SHORT FIN MODULES



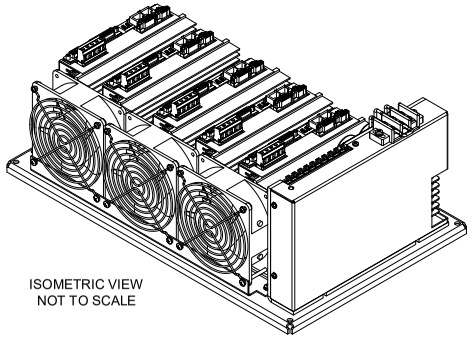


DRAWING # 9GE15-1010-008 | SCALE: .75:1 | DRAWN BY: M. TAGUPA | DATE: 18MAR22

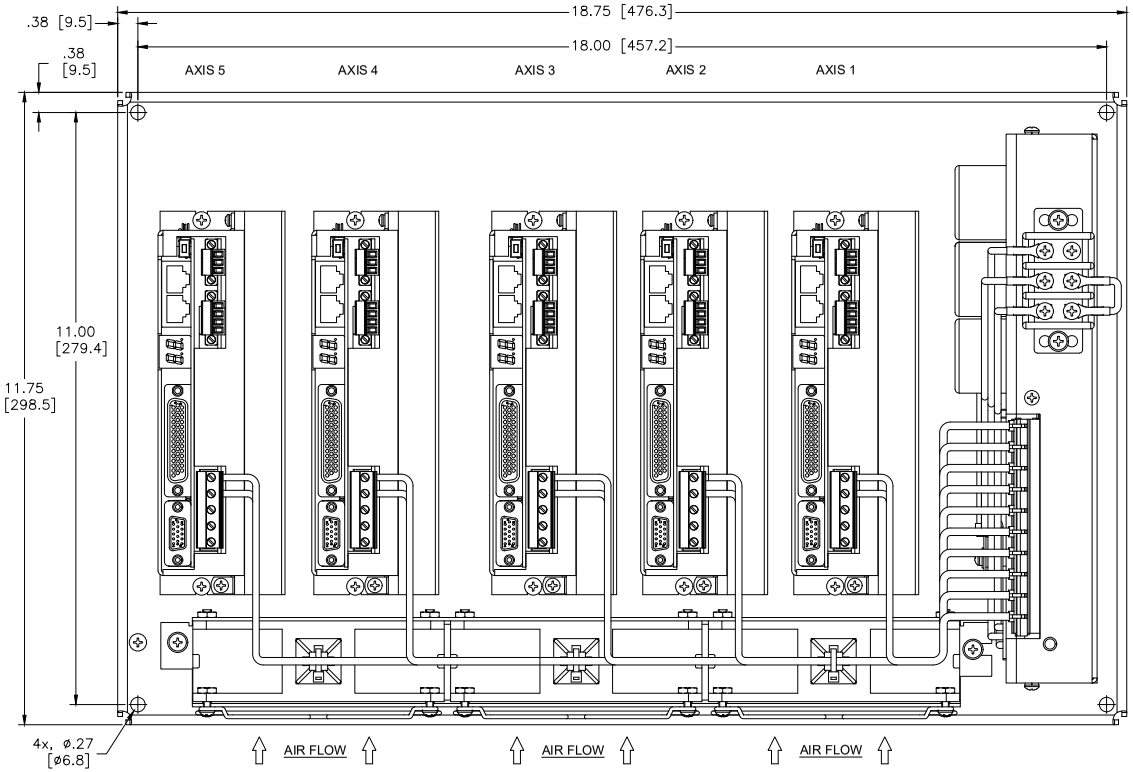
UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES

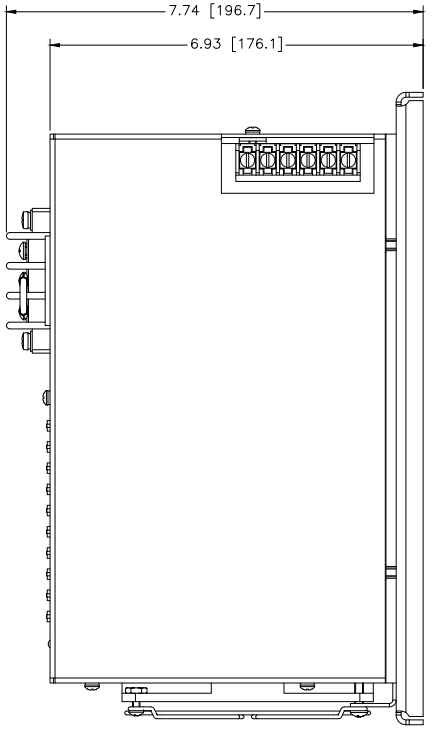
TOLERANCES AS FOLLOWS: DECIMAL: .XX = ±0.01 .XXX = ±0.005 ANGULAR < = ±0.5°

9GE15 5-AXIS PACKAGE: L-BRACKET OR SHORT FIN MODULES



ISOMETRIC VIEW
NOT TO SCALE





DRAWING # 9GE15-1010-009	SCALE: .625:1	DRAWN BY: M. TAGUPA	DATE: 18MAR22	UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES	TOLERANCES AS FOLLOWS: DECIMAL: .XX = ± 0.01 .XXX = ± 0.005 ANGULAR < = ± 0.5°

STAND ALONE MODEL NUMBERING

SM ☐ 9GE ☐ - ☐☐ - ☐☐☐ - ☐☐☐☐ 0 - 1 ☐ - 1 - ☐

On-Board or External Bus Logic [1]	
B	Bus Power Logic
C	24 VDC External Logic Power, Keep Alive

Drive Model [2]			
15	5 to 45 A Models	**45**	45 A Models
30	30 A Models	**75**	75 A Models

Input Voltage [2]					
1	110-130 VAC	**2**	208-240 VAC	**3**	360-400 VAC

Continuous Output Current [2]							
1	5 A	**4**	15 A	**6**	25 A	**8**	45 A
3	10 A	**5**	20 A	**7**	30 A	**9**	75 A

Operation Modes (Insert a 0 if the option is not included, or a 1 if it is included)
Brushless Mode - Analog & PWM Input, Current, Velocity, or Position Mode (Pulse Follower)
Brush Mode - Analog & PWM Input, Current, Velocity, or Position Mode (Pulse Follower)
External Sine Commutation / 2 Phase Current Mode [3]

Feedback Options	
A	No feedback devices
B	TTL Quadrature Encoder and/or Hall Sensor/Commutation Track
C	Analog Sin/Cos Encoder and/or Hall Sensor/Commutation Track
D	Resolver
E	Absolute Encoder without Analog Sin/Cos Channels
F	Tachometer [3]
G	Absolute Encoder with Analog Sin/Cos Channels
Z	Special

Communication Options			
A	RS-232 (Standard)	**C**	CANopen
B	EtherCAT	**D**	RS-485

Special Features (Available at additional cost) (Insert a 0 if the option is not included, or a 1 if it is included)
Safe Torque Off (STO) [4]
Encoder Divider

Stand Alone Package Configuration	
A	Built In Regen Clamp with dissipation resistor and fan(s) (Standard for drives with a cont. current ≥20 amps)
B	No Built In Regen Clamp
C	Custom (Contact Glentek)
F	Built in Regen Clamp without dissipation resistor nor fan [5]

Fan Voltage					
0	No Fan	**1**	115 VAC	2	230 VAC

Notes (For 9GE Stand Alone models):

[1] Bus power logic (SMB models) not available for input voltages of greater than 360 VAC.

[2] Refer to the Electrical Ratings on pg. 2 for available combinations of voltage and current.

[3] External sine commutation and tachometer may not both be selected.

[4] Safe Torque Off (STO) option might require longer lead times, depending on the model.

[5] External forced air cooling must be supplied for rated current.

MODULE MODEL NUMBERING

SM [ ] 9GE15 - [ ][ ] - [ ][ ][ ] - [ ][ ][ ][ ] 0 - 1

On-Board or External Bus Logic [1]	
B	Bus Power Logic
C	24 VDC External Logic Power, Keep Alive

Input Voltage [2]			
0	24-60 VDC	**2**	190-370 VDC
1	60-190 VDC	**3**	370-565 VDC

Continuous Output Current [2]					
1	5 A	**5**	20 A	**8**	45 A
3	10 A	**6**	25 A	**-**	-
4	15 A	**7**	30 A	**-**	-

Operation Modes (Insert a 0 if the option is not included, or a 1 if it is included)
Brushless Mode - Analog & PWM Input, Current, Velocity, or Position Mode (Pulse Follower)
Brush Mode - Analog & PWM Input, Current, Velocity, or Position Mode (Pulse Follower)
External Sine Commutation / 2 Phase Current Mode [3]

Feedback Options	
A	No feedback devices
B	TTL Quadrature Encoder and/or Hall Sensor/Commutation Track
C	Analog Sin/Cos Encoder and/or Hall Sensor/Commutation Track
D	Resolver
E	Absolute Encoder without Analog Sin/Cos Channels
F	Tachometer [3]
G	Absolute Encoder with Analog Sin/Cos Channels
Z	Special

Communication Options			
A	RS-232 (Standard)	**C**	CANopen
B	EtherCAT	**D**	RS-485

Special Features (Available at additional cost) (Insert a 0 if the option is not included, or a 1 if it is included)
Safe Torque Off (STO) [4]
Encoder Divider

Notes (For 9GE Stand Alone, Module, and Multi-Axis models):

[1] Bus power logic (SMB models) not available for input voltages of greater than 370 VDC (Module) or 360 VAC (Stand Alone and Multi-Axis).

[2] Refer to the Electrical Ratings on pg. 2 for available combinations of voltage and current.

[3] External sine commutation and tachometer may not both be selected.

[4] Safe Torque Off (STO) option might require longer lead times, depending on the model.

MULTI-AXIS MODEL NUMBERING

SM ☐ 9GE15 - ☐☐ - ☐☐☐ - ☐☐☐☐ 0 - ☐☐ - ☐ - ☐

On-Board or External Bus Logic (1)	
B	Bus Power Logic
C	24 VDC External Logic Power, Keep Alive

Input Voltage (2)			
1	110-130 VAC	**3**	360-400 VAC
2	208-240 VAC	**-**	-

Continuous Output Current (2)					
1	5 A	**5**	20 A	**8**	45 A
3	10 A	**6**	25 A	**-**	-
4	15 A	**7**	30 A	**-**	-

Operation Modes (Insert a 0 if the option is not included, or a 1 if it is included)
Brushless Mode - Analog & PWM Input, Current, Velocity, or Position Mode (Pulse Follower)
Brush Mode - Analog & PWM Input, Current, Velocity, or Position Mode (Pulse Follower)
External Sine Commutation / 2 Phase Current Mode (3)

Feedback Options	
A	No feedback devices
B	TTL Quadrature Encoder and/or Hall Sensor/Commutation Track
C	Analog Sin/Cos Encoder and/or Hall Sensor/Commutation Track
D	Resolver
E	Absolute Encoder without Analog Sin/Cos Channels
F	Tachometer (3)
G	Absolute Encoder with Analog Sin/Cos Channels
Z	Special

Communication Options			
A	RS-232 (Standard)	**C**	CANopen
B	EtherCAT	**D**	RS-485

Special Features (Available at additional cost) (Insert a 0 if the option is not included, or a 1 if it is included)
Safe Torque Off (STO) (4)
Encoder Divider

Mounting Configuration					
2	2-Axis Chassis	**4**	4-Axis Chassis	**5**	5-Axis Chassis

Multi-Axis Package Configuration	
A	Built In Regen Clamp with Dissipation Resistor (Standard)
B	No Built In Regen Clamp
C	Custom (Contact Glentek)

Number of Drive Modules Installed			
1	1 Drive Module (2-Axis Chassis)	**4**	4 Drive Modules (4-Axis Chassis)
2	2 Drive Modules (2-Axis Chassis)	**5**	5 Drive Modules (5-Axis Chassis)
3	3 Drive Modules (4-Axis Chassis)	-	-

Fan Voltage			
1	115 VAC	**2**	230 VAC

For notes, refer to pg. 25.